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MATH 250 : LINEAR ALGEBRA

Midterm Exam 1 – KEY

M1–1 Consider $g : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by

$$g(x, y) := (x, y^2),$$

and let \mathcal{L} be the line segment connecting $(0, 0)$ to $(2, 1)$. What is the image $g(\mathcal{L})$? Sketch a picture, and give as precise a mathematical description as you can.

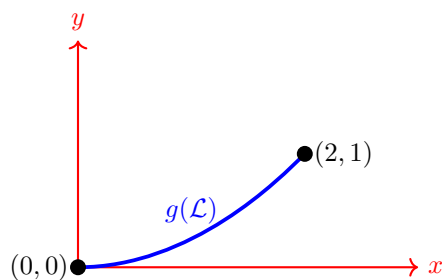
First observe that we can express \mathcal{L} as a set of points:

$$\mathcal{L} = \{(2t, t) : 0 \leq t \leq 1\}.$$

It follows that

$$g(\mathcal{L}) = \{g(2t, t) : 0 \leq t \leq 1\} = \{(2t, t^2) : 0 \leq t \leq 1\}.$$

If we label the first coordinate as x and the second as y , we see that all of these points satisfy the condition $y = \frac{1}{4}x^2$. Thus, the points of $g(\mathcal{L})$ are precisely those points on the parabola $y = \frac{1}{4}x^2$ with $0 \leq x \leq 2$. Here's a picture:



M1–2 Carefully explain why $f(f^{-1}(x)) = x$ for any $x \in \text{im}(f)$. What happens if $x \notin \text{im}(f)$?

Recall that the preimage of x is defined to be

$$f^{-1}(x) := \{y : f(y) = x\}.$$

If $x \notin \text{im}(f)$, then $f(f^{-1}(x)) = f(\emptyset) = \emptyset$. If $x \in \text{im}(f)$, then $f^{-1}(x) \neq \emptyset$, whence

$$\begin{aligned} f(f^{-1}(x)) &= f(\{y : f(y) = x\}) \\ &= \{f(y) : f(y) = x\} \\ &= \{x\} \\ &= x \end{aligned}$$

(recall our convention that sets consisting of a single element are indistinguishable from that element).

M1–3 Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be a linear map. In class we showed that the image of the unit square whose lower left vertex is at the origin has area $\det f$. Prove that this is true for an arbitrary unit square in the plane.

We first prove the special case of the ‘upright’ square:

Lemma 1. *Suppose $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is linear, and let S denote the unit square whose lower left corner is the origin. If S' is a translation of S , then the area of $f(S')$ is $\det f$.*

Proof. Label the lower left corner of S' as (p, q) , so $S' = (p, q) + S$. Then the other corners of S' are located at $(p + 1, q)$, $(p, q + 1)$, and $(p + 1, q + 1)$. Problem 4.7 implies that the image of S' is the quadrilateral with vertices

$$f(p, q), \quad f(p + 1, q), \quad f(p + 1, q + 1), \quad \text{and} \quad f(p, q + 1).$$

By additivity, we can rewrite these in the form

$$f(p, q) + f(0, 0), \quad f(p, q) + f(1, 0), \quad f(p, q) + f(1, 1), \quad \text{and} \quad f(p, q) + f(0, 1).$$

Thus $f(S') = f(p, q) + f(S)$, i.e., $f(S')$ is simply a translation of $f(S)$. It follows that

$$\text{area } f(S') = \text{area } f(S) = \det f$$

as claimed. □

Our goal is to bootstrap from this special case to the general case. But first, we arm ourselves with one more preparatory result:

Lemma 2. *Given an arbitrary unit square $T \subseteq \mathbb{R}^2$, there exists an angle α such that $R_\alpha(T)$ is an upright square (i.e., the sides of $R_\alpha(T)$ are parallel to the coordinate axes).*

Proof. If T is upright, we’re done (take $\alpha = 0$). Thus we may suppose T is not upright. It follows that T has a side with positive slope; label the endpoints of this side A and B . We define a function $g : \mathbb{R} \rightarrow \mathbb{R}$ by setting $g(\theta)$ to be the slope of the line segment $R_\theta(\overline{AB})$. Note that g is a continuous function, and that $g(0) > 0 > g(\frac{\pi}{2})$. By the intermediate value theorem, there exists an α between 0 and $\frac{\pi}{2}$ such that $g(\alpha) = 0$. Thus one side of $R_\alpha(T)$ is parallel to the horizontal axis; this implies $R_\alpha(T)$ is an upright square. □

We are now in a position to handle the general case.

Proposition 3. *Suppose $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is linear. If T is an arbitrary unit square in the plane, then $\text{area } f(T) = \det f$.*

Proof. By Lemma 2, there exists $\alpha \in \mathbb{R}$ such that $S' := R_\alpha(T)$ is an upright unit square. It follows that $T = R_{-\alpha}(S')$, whence

$$f(T) = (f \circ R_{-\alpha})(S').$$

Lemma 1 implies that

$$\begin{aligned} \text{area } f(T) &= \det(f \circ R_{-\alpha}) \\ &= (\det f)(\det R_{-\alpha}) \\ &= \det f \end{aligned}$$

since for any θ we have $\det R_\theta = \cos^2 \theta + \sin^2 \theta = 1$. □

M1-4 In class we've considered several times the linear map $\rho : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which reflects across the horizontal axis. In this problem we explore the more general reflection $\sigma_{\mathcal{L}} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ across a given line \mathcal{L} .

(a) Prove that $R_{\theta} \circ \rho = \rho \circ R_{-\theta}$.

From class we know that

$$R_{\theta} = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad \text{and} \quad \rho = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}.$$

Thus

$$R_{\theta} \circ \rho = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \circ \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$$

while

$$\rho \circ R_{-\theta} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \circ \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$$

The claim follows. □

(b) Prove that if \mathcal{L} is a line passing through the origin, then $\sigma_{\mathcal{L}}$ is linear. [*Hint: Write $\sigma_{\mathcal{L}}$ as a composition of linear maps.*]

[See illustration on next page.] To find where the reflection map $\sigma_{\mathcal{L}}$ sends a point x , we can tilt our head until \mathcal{L} is horizontal (or vertical), then flip over this axis, and then finally until our head. Let's translate this into the language of linear algebra:

$$\sigma_{\mathcal{L}} = R_{\theta} \circ \rho \circ R_{-\theta}$$

(For a rigorous proof, see Lemma below.) Since all three of these operations are linear, their composition must also be linear. □

Lemma 4. $\sigma_{\mathcal{L}} = R_{\theta} \circ \rho \circ R_{-\theta}$

Proof due to Yuxin Wu. Let θ denote the angle formed between \mathcal{L} and the positive horizontal axis. Set

$$p := R_{\theta} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad q := R_{\theta} \begin{pmatrix} 0 \\ 1 \end{pmatrix}.$$

Then $\sigma_{\mathcal{L}}(p) = p$ and $\sigma_{\mathcal{L}}(q) = -q$. It follows that

$$\sigma_{\mathcal{L}} \circ R_{\theta} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = R_{\theta} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad \sigma_{\mathcal{L}} \circ R_{\theta} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = R_{\theta} \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

whence

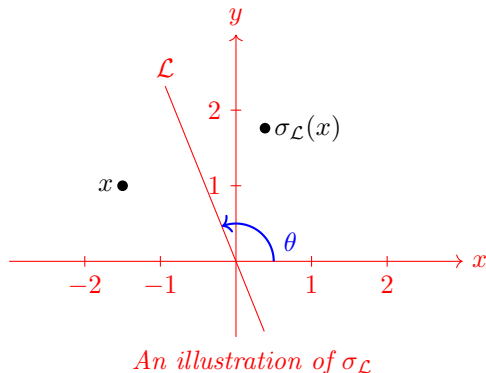
$$R_{-\theta} \circ \sigma_{\mathcal{L}} \circ R_{\theta} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and} \quad R_{-\theta} \circ \sigma_{\mathcal{L}} \circ R_{\theta} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ -1 \end{pmatrix}$$

This implies that

$$R_{-\theta} \circ \sigma_{\mathcal{L}} \circ R_{\theta} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \rho.$$

The claim follows. □

Label as θ the angle formed by \mathcal{L} and the positive part of the horizontal axis:



(c) Suppose \mathcal{L} and \mathcal{L}' are two distinct lines in the plane, both passing through the origin. Describe $\sigma_{\mathcal{L}} \circ \sigma_{\mathcal{L}'}$ geometrically, with justification. [Hint: Use parts (a) and (b).]

Applying part (a) to part (b), we see that $\sigma_{\mathcal{L}} = R_{\alpha} \circ \rho$ for some α . (In fact, $\alpha = 2\theta$, where θ is the angle illustrated above.) Similarly, $\sigma_{\mathcal{L}'} = R_{\beta} \circ \rho$ for some β . Applying (a) yields

$$\sigma_{\mathcal{L}} \circ \sigma_{\mathcal{L}'} = R_{\alpha} \circ \rho \circ R_{\beta} \circ \rho = R_{\alpha} \circ R_{-\beta} \circ \rho \circ \rho = R_{\alpha-\beta}.$$

Thus $\sigma_{\mathcal{L}} \circ \sigma_{\mathcal{L}'}$ is a rotation.

M1–5 We say a function $\phi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is *distance-preserving* iff

$$|\phi(x) - \phi(y)| = |x - y| \quad \forall x, y \in \mathbb{R}^2.$$

In other words, the distance between the images of any two points is the same as the distance between the two points themselves.

(a) Give an example of a distance-preserving function which is not a linear map.

Let $T_k : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the translation map, defined by

$$T_k(x) := x + k.$$

Then for any two points $x, y \in \mathbb{R}^2$, we have

$$|T_k(x) - T_k(y)| = |(x + k) - (y + k)| = |x - y|$$

so T_k is distance-preserving. On the other hand, T_k cannot be linear for any $k \neq \mathbf{0}$, since $T_k(\mathbf{0}) \neq \mathbf{0}$.

(b) Suppose $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is distance-preserving and satisfies $f(\mathbf{0}) = \mathbf{0}$. Prove that $|f(x)| = |x|$ for all $x \in \mathbb{R}^2$.

By the definition of distance-preserving, we have

$$|f(x)| = |f(x) - f(\mathbf{0})| = |x - \mathbf{0}| = |x|$$

for any $x \in \mathbb{R}^2$. □

(c) Suppose f is as in (b). Prove that $f(x) \cdot f(y) = x \cdot y$ for all $x, y \in \mathbb{R}^2$. [Hint: Start with the distance-preserving relation $|f(x) - f(y)| = |x - y|$.]

Using properties of dot products, as well as part (b), we see

$$\begin{aligned} |f(x) - f(y)|^2 &= (f(x) - f(y)) \cdot (f(x) - f(y)) \\ &= f(x) \cdot f(x) - 2(f(x) \cdot f(y)) + f(y) \cdot f(y) \\ &= |f(x)|^2 + |f(y)|^2 - 2(f(x) \cdot f(y)) \\ &= |x|^2 + |y|^2 - 2(f(x) \cdot f(y)). \end{aligned}$$

On the other hand, since f is distance preserving, we have

$$|f(x) - f(y)|^2 = |x - y|^2 = (x - y) \cdot (x - y) = x \cdot x - 2(x \cdot y) + y \cdot y = |x|^2 + |y|^2 - 2(x \cdot y).$$

The claim immediately follows. \square

(d) Suppose f is as in (b). Prove that f must be linear. [Hint: First prove that $|f(\alpha x) - \alpha f(x)| = 0$.]

As usual, to prove that f is linear we must verify that it's additive and scales.

Scaling. Given $\alpha \in \mathbb{R}$ and $x \in \mathbb{R}^2$ we have

$$\begin{aligned} |f(\alpha x) - \alpha f(x)|^2 &= (f(\alpha x) - \alpha f(x)) \cdot (f(\alpha x) - \alpha f(x)) \\ &= f(\alpha x) \cdot f(\alpha x) - 2\alpha(f(x) \cdot f(\alpha x)) + \alpha^2(f(x) \cdot f(x)) \\ &= (\alpha x) \cdot (\alpha x) - 2\alpha(x \cdot \alpha x) + \alpha^2(x \cdot x) \\ &= 0. \end{aligned}$$

It follows that $|f(\alpha x) - \alpha f(x)| = 0$, whence $f(\alpha x) = \alpha f(x)$ as claimed.

Additivity. Given $x, y \in \mathbb{R}^2$, we have

$$|f(x + y) - f(x) - f(y)|^2 = (f(x + y) - f(x) - f(y)) \cdot (f(x + y) - f(x) - f(y)).$$

Expanding this, using part (b), and simplifying yields

$$|f(x + y) - f(x) - f(y)|^2 = 0.$$

This implies that $f(x + y) = f(x) + f(y)$ as claimed.

Combining both of the above properties proves that f must be linear. \square

(e) Suppose f is as in (b). Prove that there exists $\theta \in \mathbb{R}$ such that either $f = R_\theta$ or $f = R_\theta \circ \rho$. Here $\rho : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ is the reflection across the horizontal axis, i.e., $\rho(x, y) := (x, -y)$.

By part (d) we know f is linear, hence can be written as a matrix. The first column of this matrix is $f(1, 0)$ and the second is $f(0, 1)$, so it suffices to figure out what these can be. By part (b), we know that

$$|f(1, 0)| = |(1, 0)| = 1,$$

which means $f(1, 0)$ lies on the unit circle centered at the origin. Thus there exists some θ such that

$$f(1, 0) = (\cos \theta, \sin \theta).$$

Next, by part (c) we have

$$f(1, 0) \cdot f(0, 1) = (1, 0) \cdot (0, 1) = 0,$$

whence $f(1, 0)$ and $f(0, 1)$ are perpendicular. Since $f(0, 1)$ also lies on the unit circle, we deduce that either

$$f(0, 1) = \left(\cos \left(\theta + \frac{\pi}{2} \right), \sin \left(\theta + \frac{\pi}{2} \right) \right) = (-\sin \theta, \cos \theta)$$

or

$$f(0, 1) = \left(\cos \left(\theta - \frac{\pi}{2} \right), \sin \left(\theta - \frac{\pi}{2} \right) \right) = (\sin \theta, -\cos \theta).$$

Putting all this together, we conclude that there exists $\theta \in \mathbb{R}$ such that either

$$f = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \quad \text{or} \quad f = \begin{pmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{pmatrix}$$

In the former situation, $f = R_\theta$; in the latter, $f = R_\theta \circ \rho$ (see **M1-4(a)** above). \square

(f) Prove that any distance-preserving map $\phi : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ can be written as the composition of a translation, a rotation, and (possibly) a reflection. [A *translation* is a map $T_k : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T_k(x) := x + k$. I'm asking you to prove that either $\phi = T_k \circ R_\theta$ or $\phi = T_k \circ R_\theta \circ \rho$.]

Consider the function

$$f := T_{-\phi(\mathbf{0})} \circ \phi.$$

From **M1-5(a)**, we know that any translation is distance-preserving. It follows that for any $x, y \in \mathbb{R}^2$, $|f(x) - f(y)| = |(T_{-\phi(\mathbf{0})} \circ \phi)(x) - (T_{-\phi(\mathbf{0})} \circ \phi)(y)| = |\phi(x) - \phi(y)| = |x - y|$; thus f is distance-preserving. Also, $f(\mathbf{0}) = (T_{-\phi(\mathbf{0})} \circ \phi)(\mathbf{0}) = \phi(\mathbf{0}) - \phi(\mathbf{0}) = \mathbf{0}$. The map f therefore satisfies the hypotheses of part (e), and thus $\exists \theta$ such that $f = R_\theta$ or $f = R_\theta \circ \rho$. Since $\phi = T_{\phi(\mathbf{0})} \circ f$, we conclude that either $\phi = T_{\phi(\mathbf{0})} \circ R_\theta$ or $\phi = T_{\phi(\mathbf{0})} \circ R_\theta \circ \rho$. \square