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Distinct Angles and Angle Chains in \mathbb{R}^3

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Joint work with Livia Betti, Jacob Lehmann Duke, Xuyan Liu, Wyatt Milgrim, Francisco Romero, and Santiago Velazquez Advisors: Steven J. Miller and Eyvindur Palsson

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• Erdős and Purdy, 1995: For a configuration of *n* noncolinear points in the plane, what is the minimum number of distinct angles between pairs of points?



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 - Upper bound: n 2 (regular *n*-gon)
 - Lower bound: *n*/6 (arises from progress on the Weak Dirac Conjecture)



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- Instead, let's restrict the points to general position:
 - No 3 colinear points
 - No 4 cocircular points

Distinct Angles in Two Dimensions

Theorem (FKMPPW 2022): Let A_{gen} be the minimum number of distinct angles formed by *n* points on a plane, with no three points on a line and no four points on a circle. Then, $A_{gen} = O(n^2)$.

 Background
 Angles in ℝ³
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 Conclusion

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• To prove this, they distributed points on a *logarithmic spiral*.



Rotate three points along the spiral to repeat the same angle!

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Rotate three points along the spiral to repeat the same angle!

- **Self-similarity**: Any angle formed by three of the points can also be formed using a special point *A* as one of the points.
- $\binom{n}{2}$ ways to choose the remaining two points, so $O(n^2)$ angles.

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Distinct Angle Chains

Conclusion

Distinct Angles in Two Dimensions

Theorem: Let A_{gen} be the minimum number of distinct angles formed by *n* points on a plane, with no three points on a line and no four points on a circle. Then, $A_{gen} = \Omega(n)$.

• Fix two points A and B and consider only angles with A as an endpoint and B as the center point.



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- We can only form a given angle twice without putting three points on a line.



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• In three dimensions, there is more room in which to move around, potentially allowing for fewer distinct angles.

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Background	Angles in \mathbb{R}^3	Distinct Angle Chains	Conclusion
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Cones and	Spindle Tori		

- In three dimensions, there is more room in which to move around, potentially allowing for fewer distinct angles.
- Now if we fix A as an endpoint and B as the center point, we can put all remaining points on a cone to form only one distinct angle.



Background Angles in \mathbb{R}^3	Distinct Angle Chains	Co

Cones and Spindle Tori

- In three dimensions, there is more room in which to move around, potentially allowing for fewer distinct angles.
- Now if we fix A as an endpoint and B as the center point, we can put all remaining points on a cone to form only one distinct angle.
- If we fix A and B as endpoints, we can put all remaining points on a spindle torus to form only one distinct angle.



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Distinct Angles in Three Dimensions

- What lower bound can we get on the number of distinct angles in three dimensions with no three points on a line and no four points on a circle?
- Using the extra space that we have in 3D, can we find a construction with $o(n^2)$ distinct angles?

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• We can manipulate the distance of each point from *A*, so that any point besides *A* lies on a sphere of radius 1 centered at *A*.



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- We can manipulate the distance of each point from A, so that any point besides A lies on a sphere of radius 1 centered at A.
- The measure of $\angle BAC$ is a constant multiple of the spherical distance between B and C.



Theorem (Guth and Katz, 2015)

A set of *n* points in the plane determines $\Omega\left(\frac{n}{\log n}\right)$ distinct distances.

Generalizing to sphere (Tao)

A set of *n* points on a sphere determines $\Omega\left(\frac{n}{\log n}\right)$ distinct distances.

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Determining the number of distinct angles with fixed center point A is equivalent to determining the number of distinct distances for these points lying on a sphere of radius 1 centered at A.

Corollary

The number of distinct angles for n points in general position in \mathbb{R}^3 with a fixed center point is $\Omega\left(\frac{n}{\log n}\right)$.

This is also the best known lower bound for distinct angles in three dimensions in general, counting all angles.

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Note: By distributing points along a circle on the sphere, we get an O(n) upper bound on the minimum number of distinct angles with a fixed center point. The lower and upper bounds are very close together!

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• Fix another point *B*.

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- Fix another point *B*.
- If A and B are both endpoints:



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Background	Angles in \mathbb{R}^3	Distinct Angle Chains	Conclusion

- Fix another point *B*.
- If A is an endpoint and B is a center point:



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• The intersection of a cone and spindle torus with the same axis is a circle. We only allow 3 points on this circle!



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- So, the number of cones multiplied by the number of spindle tori must be at least (n-2)/3.



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- There are at least $max(#{cones}, #{s. tori})$ distinct angles.



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- The intersection of a cone and spindle torus with the same axis is a circle. We only allow 3 points on this circle!
- So, the number of cones multiplied by the number of spindle tori must be at least (n-2)/3.
- There are at least $max(\#\{cones\}, \#\{s. tori\})$ distinct angles.
- To minimize this, $\#\{\text{cones}\} = \#\{\text{s. tori}\} = \sqrt{(n-2)/3}$.



Background	Angles in ℝ³	Distinct Angle Chains	Conclusion
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• We now have $O(n^2)$ and $\Omega(\sqrt{n})$ as upper and lower bounds for minimum number of distinct angles with a pinned endpoint.

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- These bounds are very far apart!
- We conjecture that it is the lower bound that can be improved.

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- We now have $O(n^2)$ and $\Omega(\sqrt{n})$ as upper and lower bounds for minimum number of distinct angles with a pinned endpoint.
- These bounds are very far apart!
- We conjecture that it is the lower bound that can be improved.

Conjecture

For any construction in general position in \mathbb{R}^3 , there are $\Omega(n^2)$ distinct angles formed when an endpoint is pinned - the same (up to a constant) as with no pinned points.

• Even without a proof of this conjecture, it's clear that pinning an endpoint and pinning a center point lead to radically different results. Background 0000 Distinct Angle Chains

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3D Constructions



To the left, points are distributed along a **cylindrical helix**, parametrized by $(\cos(t), \sin(t), t)$. To the right, points are distributed on a **conchospiral**, parametrized by $(e^t \cos(t), e^t \sin(t), e^t)$. Due to their symmetry, both of these point configurations exhibit self-similarity and thus have $O(n^2)$ distinct angles.



- In two dimensions, general position means no three colinear points and no four cocircular points.
- In three dimensions, we keep this definition rather than disallowing 4 coplanar points or 5 cospherical points.
 - Our constructions (upper bound) are still valid under this restriction.

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• No obvious improved lower bound.



- In two dimensions, general position means no three colinear points and no four cocircular points.
- In three dimensions, we keep this definition rather than disallowing 4 coplanar points or 5 cospherical points.
 - Our constructions (upper bound) are still valid under this restriction.
 - No obvious improved lower bound.
- We could disallow having too many points on any surface of degree 2.
 - Doing so would improve our lower bound from $\Omega(n/\log n)$ to $\Omega(n)$.

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• But, all our constructions would be invalid and our upper bound would worsen to $O(n^2 2^{C\sqrt{\log n}})$.

Background	Angles in ℝ ³	Distinct Angle Chains	Conclusion
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"General posi	tion" in 3D		

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 We can also relax the general position requirement, for example allowing O(√n) points on a line or on a circle.



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Permitting $O(\sqrt{n})$ points on lines and circles allows for a configuration with O(n) distinct angles with a pinned endpoint.

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Distinct And	ale Chains		
Background	Angles in R ^o	Distinct Angle Chains	Conclusion
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• A *k*-chain is a (k + 2)-tuple of points (x_1, \ldots, x_{k+2}) along with the associated *k*-tuple of angles

$$(\alpha_1,\ldots,\alpha_k)=(\angle x_1x_2x_3,\ldots,\angle x_kx_{k+1}x_{k+2}).$$



A sample three-chain in \mathbb{R}^2

• There are *n* points in space with no three points on a line and no four points on a circle. For a given *k*, what is the minimum number of distinct *k*-tuples such that there exists a *k*-chain with those angles?

Distinct A	ngle Chains		
Background	Angles in \mathbb{R}^3	Distinct Angle Chains	Conclusion
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A sample three-chain in \mathbb{R}^2

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- There are *n* points in space with no three points on a line and no four points on a circle. For a given *k*, what is the minimum number of distinct *k*-tuples such that there exists a *k*-chain with those angles?
- If k = 1, this is just the question we already asked.

Background	Angles in \mathbb{R}^3	Distinct Angle Chains	Conclusion
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Distinct Angle	Chains in 2D		

- Recall: In 2D, if one endpoint and the center point of the angle are fixed, we get Ω(n) angles since no three points are on a line.
- So, adding one leg to the chain must multiply the number of distinct angle chains by Ω(n).

Background	Angles in \mathbb{R}^3	Distinct Angle Chains	Conclusion
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- Recall: In 2D, if one endpoint and the center point of the angle are fixed, we get Ω(n) angles since no three points are on a line.
- So, adding one leg to the chain must multiply the number of distinct angle chains by Ω(n).
- By induction:

Theorem (RBLLMMPRV 2022)

For n points in general position in two dimensions, there are $\Omega(n^k)$ distinct k-tuples of angles with associated k-chains.

Background	Angles in ℝ ³	Distinct Angle Chains	Conclusion
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Distinct And	le Chains in 2D		

• The logarithmic spiral provides the best upper bound we could hope for in two dimensions.

Theorem (**R**BLLMMPRV 2022)

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With points distributed on the logarithmic spiral, there are $O(n^{k+1})$ distinct k-tuples of angles with associated k-chains.





- In 3D, it is no longer true that adding a leg to the chain creates *n* choices for the new angle.
- We have the following weaker lower bound on the number of distinct angle *k*-chains.

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Background	Angles in \mathbb{R}^3	Distinct Angle Chains	Conclusion
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Distinct Angle	Chains in 3D		

- In 3D, it is no longer true that adding a leg to the chain creates *n* choices for the new angle.
- We have the following weaker lower bound on the number of distinct angle *k*-chains.

Theorem (RBLLMMPRV 2022)

In three dimensions, the number of distinct k-tuples of angles with associated k-chains is bounded below by:

$$\begin{cases} \Omega\left(\frac{n^{(k+2)/3}}{(\log n)^{(k+2)/3}}\right) & \text{ if } k = 1 \mod 3; \\ \Omega\left(\frac{n^{(k+1)/3}}{(\log n)^{(k-2)/3}}\right) & \text{ if } k = 2 \mod 3; \\ \Omega\left(\frac{n^{k/3+1/2}}{(\log n)^{k/3}}\right) & \text{ if } k = 0 \mod 3. \end{cases}$$

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• Takeaway: The lower bound gets multiplied by $n/\log(n)$ every time the chain gets 3 longer (compared to n^3 for 2D).

- Going forward, we hope to make progress in raising the lower bound for distinct angles in \mathbb{R}^3 with a pinned endpoint.
- This would improve bounds for the number of distinct angle chains in 3D, as would any further improvements on Agen.
- The ultimate goal would be to come up with explicit constructions that minimize the number of distinct *k*-chains for a given *k* and *n*.

Another Ap	proach		
Background	Angles in ℝ ³	Distinct Angle Chains	Conclusion
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- Another possible approach at improving the lower bound:
- \bullet For a point configuration $\mathcal{P},$ the energy is given by

$$E(\mathcal{P}) = |\{(A, B, C, D, E, F) \in \mathcal{P}^6 : \angle ABC = \angle DEF\}|.$$

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Another Ap	proach		
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$$\mathsf{E}(\mathcal{P}) = |\{(A, B, C, D, E, F) \in \mathcal{P}^6 : \angle ABC = \angle DEF\}|.$$

• For an angle α , denote

$$N_{\alpha} = |\{(A, B, C) \in \mathcal{P}^3 : \angle ABC = \alpha\}|.$$

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Another Ap	proach		
Background	Angles in \mathbb{R}^3	Distinct Angle Chains	Conclusion
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- Another possible approach at improving the lower bound:
- For a point configuration \mathcal{P} , the *energy* is given by

$$\mathsf{E}(\mathcal{P}) = |\{(\mathsf{A},\mathsf{B},\mathsf{C},\mathsf{D},\mathsf{E},\mathsf{F})\in\mathcal{P}^{\mathsf{6}}: \angle \mathsf{ABC} = \angle \mathsf{DEF}\}|.$$

• For an angle α , denote

$$N_{\alpha} = |\{(A, B, C) \in \mathcal{P}^3 : \angle ABC = \alpha\}|.$$

 $\bullet\,$ Then, if ${\cal A}$ is the set of all angles formed, we have

$$E(\mathcal{P}) = \sum_{lpha \in \mathcal{A}} N_{lpha}^2 \quad ext{and} \quad \sum_{lpha \in \mathcal{A}} N_{lpha} = |\mathcal{P}|^3 = n^3.$$

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• Cauchy-Schwarz inequality:

$$\left(\sum_{\alpha \in \mathcal{A}} N_{\alpha}\right)^2 \leq \left(\sum_{\alpha \in \mathcal{A}} N_{\alpha}^2\right) \left(\sum_{\alpha \in \mathcal{A}} 1^2\right),$$

which means

$$|\mathcal{A}| \geq \frac{n^6}{E(\mathcal{P})}.$$

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$$E(\mathcal{P}) = \sum_{lpha \in \mathcal{A}} N_{lpha}^2 \quad ext{and} \quad \sum_{lpha \in \mathcal{A}} N_{lpha} = |\mathcal{P}|^3 = n^3.$$

• Cauchy-Schwarz inequality:

$$\left(\sum_{\alpha \in \mathcal{A}} \mathsf{N}_{\alpha}\right)^2 \leq \left(\sum_{\alpha \in \mathcal{A}} \mathsf{N}_{\alpha}^2\right) \left(\sum_{\alpha \in \mathcal{A}} 1^2\right),$$

which means

$$|\mathcal{A}| \geq \frac{n^{\circ}}{E(\mathcal{P})}.$$

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An upper bound on E(P) would entail a lower bound on the number of distinct angles.

An Incidence Problem						
Background	Angles in ℝ³	Distinct Angle Chains	Conclusion			
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• An upper bound on $E(\mathcal{P})$ would entail a lower bound on the number of distinct angles.

$$E(\mathcal{P}) = |\{(A, B, C, D, E, F) \in \mathcal{P}^6 : \angle ABC = \angle DEF\}|.$$

• Note that $m \angle ABC = m \angle DEF$ if and only if

$$\frac{(A-B)\cdot(C-B)}{|A-B||C-B|} = \frac{(D-E)\cdot(F-E)}{|D-E||F-E|}.$$

Squaring both sides and rearranging:

$$((A - B) \cdot (C - B))^2 |D - E|^2 |F - E|^2 - ((D - E) \cdot (F - E))^2 |A - B|^2 |C - B|^2 = 0.$$
(1)

This defines a "nice" surface. How many times can Equation
 (1) be satisfied by a point configuration?

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Acknowledgements							

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- Alex losevich and Adam Sheffer for helpful conversations
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• University of Michigan for further funding

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