

Signal Recovery using Gowers' Norms and Gabor Transform

Say-Yeon Kwon¹ Meiling Laurence²
Iana Vranesko³

¹Princeton University, sk9017@princeton.edu

²Yale University, meiling.laurence@yale.edu

³Williams College, yv2@williams.edu

Joint work with Ivan Bortnovskiy, Lawrence Dillon, June Duvivier, Xiaoyao Huang,
Josh Iosevich, Michael Lucas, Tiancheng Pan, Pramana Saldin, and Jennifer
Smucker

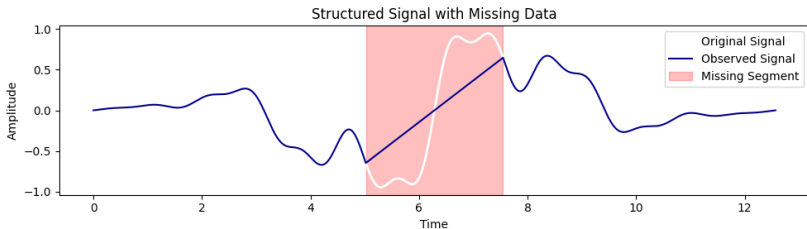
Advised by Prof. Alex Iosevich and Prof. Eyvindur Palsson

SMALL REU 2025; Yale University, July 23rd, 2025

Introduction

Can You Recover the Original Signal?

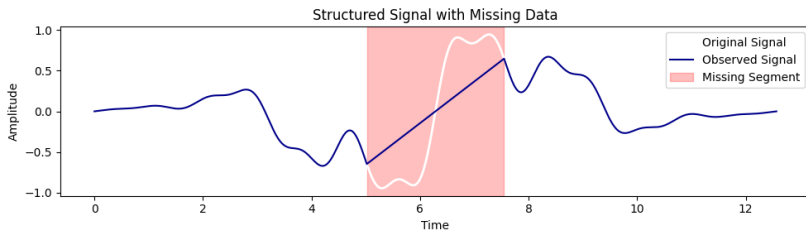
- You receive only part of a signal/frequency - the rest is missing.



(Illustrative example of a corrupted signal)

Can You Recover the Original Signal?

- You receive only part of a signal/frequency - the rest is missing.

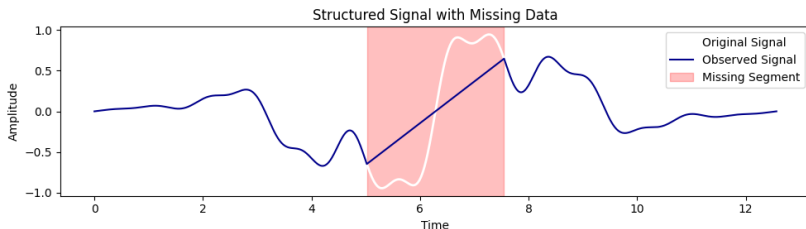


(Illustrative example of a corrupted signal)

- Is it possible to reconstruct the full message?

Can You Recover the Original Signal?

- You receive only part of a signal/frequency - the rest is missing.



(Illustrative example of a corrupted signal)

- Is it possible to reconstruct the full message?
- Sufficient conditions for reconstruction? What if you know the signal/frequency is "structured"?

Fourier Analysis and Additive Combinatorics

We'll use tools from **Fourier Analysis** and **Additive Combinatorics** to find out.

Fourier Transform

Definition (Discrete Fourier Transform)

For a function $f : \mathbb{Z}_N^d \rightarrow \mathbb{C}$, the **normalized DFT** is:

$$\widehat{f}(k) := \frac{1}{\sqrt{N^d}} \sum_{n \in \mathbb{Z}_N^d} f(n) \chi(-kn),$$

where $\chi(x) = e^{-2\pi i k \cdot x / N}$. Then, the inverse transform formula follows:

$$f(n) = \frac{1}{\sqrt{N^d}} \sum_{k \in \mathbb{Z}_N^d} \widehat{f}(k) \chi(kn).$$

Fourier Transform Notation

- We will call an arbitrary function $f : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ a **signal**.
- We will call an arbitrary function's fourier transform $\widehat{f} : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ a **frequency**.

Classical Uncertainty Principle

Theorem (Classical Uncertainty Principle)

Let $f : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ be a nonzero function with support $\text{supp}(f) \subseteq \mathbb{Z}_N^d$. Let $\widehat{f} : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ denote the discrete Fourier transform of f , with support $\text{supp}(\widehat{f}) \subseteq \mathbb{Z}_N^d$. Then the following inequality holds:

$$|\text{supp}(f)| \cdot |\text{supp}(\widehat{f})| \geq N^d.$$

- This is a discrete version of Heisenberg's Uncertainty Principle!

Discrete L_p -norm

Definition (L_p Norm)

For a function $f : \mathbb{Z}_N \rightarrow \mathbb{C}$, the L_p norm is defined as:

$$\|f\|_{L_p(\mathbb{Z}_N)} := \begin{cases} \left(\frac{1}{N} \sum_{n=0}^{N-1} |f(n)|^p \right)^{1/p} & \text{if } 1 \leq p < \infty \\ \max_{0 \leq n < N} |f(n)| & \text{if } p = \infty \end{cases}$$

Discrete L_p -norm

Definition (L_p Norm)

For a function $f : \mathbb{Z}_N \rightarrow \mathbb{C}$, the L_p norm is defined as:

$$\|f\|_{L_p(\mathbb{Z}_N)} := \begin{cases} \left(\frac{1}{N} \sum_{n=0}^{N-1} |f(n)|^p \right)^{1/p} & \text{if } 1 \leq p < \infty \\ \max_{0 \leq n < N} |f(n)| & \text{if } p = \infty \end{cases}$$

Theorem (Holder's Inequality)

For a function $f, g : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ and $\frac{1}{p} + \frac{1}{q} = 1$,

$$\|fg\|_{L^1} \leq \|f\|_{L^p} \cdot \|g\|_{L^q}$$

Unique Recovery Principle

Theorem (Classical Recovery Condition)

Let $f : \mathbb{Z}_N \rightarrow \mathbb{C}$ supported in $E \subset \mathbb{Z}_N$. Suppose that \hat{f} is transmitted but the frequencies $\{\hat{f}(m)\}_{m \in S}$ are unobserved, where $S \subset \mathbb{Z}_N$, with

$$|E| \cdot |S| < \frac{N}{2}. \quad (1)$$

Then f can be recovered exactly and uniquely. Moreover,

$$f = \arg \min_g \|g\|_{L^1(\mathbb{Z}_N)} \quad (2)$$

with the constraint $\hat{f}(m) = \hat{g}(m)$, $m \notin S$.

Gower's Norms

Gowers' Norms

Theorem (Classical Uncertainty Principle)

Let $f : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ be a nonzero function with support $\text{supp}(f) \subseteq \mathbb{Z}_N^d$. Let $\hat{f} : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ denote the discrete Fourier transform of f , with support $\text{supp}(\hat{f}) \subseteq \mathbb{Z}_N^d$. Then the following inequality holds:

$$|\text{supp}(f)| \cdot |\text{supp}(\hat{f})| \geq N^d.$$

Can we quantify the "structure" of a set more precisely than just size?

Can we quantify the "structure" of a set more precisely than just size?

Definition

The **additive energy** of a set $A \subset \mathbb{Z}^d$ is defined as:

$$\Lambda(A) := \left| \{ (x_1, x_2, x_3, x_4) \in A^4 : x_1 + x_2 = x_3 + x_4 \} \right|,$$

where $|\cdot|$ denotes the cardinality of the set.

Can we quantify the "structure" of a set more precisely than just size?

Definition

The **additive energy** of a set $A \subset \mathbb{Z}^d$ is defined as:

$$\Lambda(A) := \left| \left\{ (x_1, x_2, x_3, x_4) \in A^4 : x_1 + x_2 = x_3 + x_4 \right\} \right|,$$

where $|\cdot|$ denotes the cardinality of the set.

Definition (Gowers U^2 -norm)

For a function $f : \mathbb{Z}_N^d \rightarrow \mathbb{C}$, the Gowers U^2 norm is defined as:

$$\|f\|_{U^2}^4 := \mathbb{E}_{x, h_1, h_2} \left[f(x) \overline{f(x + h_1)} \overline{f(x + h_2)} f(x + h_1 + h_2) \right].$$

Additive Uncertainty Principle

Theorem (Additive Uncertainty Principle - Iosevich-Mayeli '25 [All⁺25])

Let $f : \mathbb{Z}_N^d \rightarrow \mathbb{C}$ be a nonzero signal with support in E , and let \hat{f} denote its Fourier transform with support in Σ . Then for any $\alpha \in [0, 1]$,

$$(i) \quad N^d \leq (|E| \cdot \Lambda^{\frac{1}{3}}(\Sigma))^{1-\alpha} \cdot (\Lambda^{\frac{1}{3}}(E) \cdot |\Sigma|)^{\alpha}.$$

To prove part (i), it is sufficient to establish the inequality

$$N^d \leq |E| \cdot \Lambda^{\frac{1}{3}}(\Sigma).$$

The inequality $N^d \leq |\Sigma| \cdot \Lambda^{\frac{1}{3}}(E)$ follows by reversing the roles of E and Σ , and the general case follows from these two by writing $N^d = N^{d(1-\alpha)} \cdot N^{d\alpha}$, $0 \leq \alpha \leq 1$. [All⁺25]

Additive Uncertainty Principle: Improved

We were able to improve the additive uncertainty principle:

Theorem (SMALL 2025)

Let $f : \mathbb{Z}_N^d \rightarrow \mathbb{C}$. Suppose f is supported on $E \subset \mathbb{Z}_N^d$ and \widehat{f} is supported on $\Sigma \subset \mathbb{Z}_N^d$. Then we have the uncertainty principle:

$$\begin{aligned} \text{(i)} \quad N^d &\leq |\Sigma| \left(\Lambda_2(E) - |E|^2 \left(1 - \sqrt{\frac{N^d}{|E||\Sigma|}} \sqrt{\frac{\Lambda_2(E)}{|E|^3}} \right) \right)^{1/3} \\ \text{(ii)} \quad N^d &\leq |\Sigma| \left(\frac{\sqrt{B_\Sigma |E| (\Lambda_2(E) - |E|^2)}}{|\Sigma|} + |E|^2 \sqrt{\frac{N^d}{|E||\Sigma|}} \sqrt{\frac{\Lambda_2(E)}{|E|^3}} \right)^{1/3}, \\ &\text{where } B_\Sigma = |\Sigma - \Sigma| |(\Sigma + \Sigma) - (\Sigma + \Sigma)| \end{aligned}$$

Additive Uncertainty Principle: Improved

Define

$$1_{x,y,a} := 1_E(x) 1_E(y) 1_E(x+a) 1_E(y+a).$$

We begin by applying the Cauchy-Schwarz inequality to the following sum:

$$\begin{aligned} & \sum_{x,y,a \in \mathbb{Z}_N^d} |f(x)f(y)f(x+a)f(y+a)| \cdot 1_{x,y,a} \\ & \leq \left(\sum_{x,y,a \in \mathbb{Z}_N^d} |f(x)f(x+a)|^2 \cdot 1_{x,y,a} \right)^{1/2} \left(\sum_{x,y,a \in \mathbb{Z}_N^d} |f(y)f(y+a)|^2 \cdot 1_{x,y,a} \right)^{1/2} \\ & = \sum_{x,y,a \in \mathbb{Z}_N^d} |f(x)f(x+a)|^2 \cdot 1_{x,y,a} \\ & = (*) \end{aligned}$$

Additive Uncertainty Principle: Improved

$$\begin{aligned}
 (*) &= N^{-2d} \sum_{m_1, \dots, m_4} \widehat{f}(m_1) \overline{\widehat{f}(m_2)} \widehat{f}(m_3) \overline{\widehat{f}(m_4)} \\
 &\quad \times \sum_{x, y, a} \chi(x \cdot (m_1 - m_2 + m_3 - m_4)) \chi(a \cdot (m_3 - m_4)) \cdot 1_{x, y, a} \\
 &\leq N^{-2d} \sum_{m_1, \dots, m_4} |\widehat{f}(m_1) \widehat{f}(m_2) \widehat{f}(m_3) \widehat{f}(m_4)| \\
 &\quad \times \left| \sum_{\substack{x, y, a \\ a=0}} \chi(x \cdot (m_1 - m_2 + m_3 - m_4)) \chi(a \cdot (m_3 - m_4)) 1_{x, y, a} \right| \\
 &+ N^{-2d} \sum_{m_1, \dots, m_4} |\widehat{f}(m_1) \widehat{f}(m_2) \widehat{f}(m_3) \widehat{f}(m_4)| \\
 &\quad \times \left| \sum_{\substack{x, y, a \\ a \neq 0}} \chi(x \cdot (m_1 - m_2 + m_3 - m_4)) \chi(a \cdot (m_3 - m_4)) 1_{x, y, a} \right| \\
 &=: S_1 + S_2
 \end{aligned}$$

Additive Uncertainty Principle: Improved

By applying Cauchy-Schwarz and Hölder's inequalities as well as exploiting the properties of $\chi(x)$, we get the following inequalities

$$\begin{aligned}
 S_1 &\leq N^{-2d} |E|^2 |\Sigma|^3 \sqrt{\frac{N^d}{|E| |\Sigma|}} \sqrt{\frac{\Lambda_2(E)}{|E|^3}} \left(\sum_m |\hat{f}(m)|^4 \right) \\
 S_2 &\leq N^{-2d} (\Lambda_2(E) - |E|^2) |\Sigma|^3 \left(\sum_{m \in \Sigma} |\hat{f}(m)|^4 \right) \quad \text{or} \\
 &\leq N^{-2d} \frac{\sqrt{B_\Sigma |E| (\Lambda_2(E) - |E|^2)}}{|\Sigma|} |\Sigma|^3 \left(\sum_{m \in \Sigma} |\hat{f}(m)|^4 \right),
 \end{aligned}$$

where $B_\Sigma = |\Sigma - \Sigma| |(\Sigma + \Sigma) - (\Sigma + \Sigma)|$.

Additive Uncertainty Principle: Improved

We are getting the statement of our new theorem by estimating the original $N^{3d} \cdot \|f\|_{U_2}^4$ from below:

$$\sum_{x,y,a \in \mathbb{Z}_N^d} |f(x)f(y)f(x+a)f(y+a)| \cdot 1_{x,y,a} \geq N^d \sum_m |\widehat{f}(m)|^4$$

Gabor Transform

What happens if we send a signal multiple times?

Theorem (Burstein et al '25 [BIMN25])

Let $f : \mathbb{Z}_N \rightarrow \mathbb{C}$, and suppose that f is transmitted but the values $\{f(x)\}_{x \in M}$ are unobserved. Suppose that

$$\|\widehat{f}\|_{L^1(S^c)} \leq \frac{\varepsilon}{N} \|\widehat{f}\|_{L^1(\mathbb{Z}_N)}. \quad (3)$$

Also suppose that $2|M||S| < N$. Let $g = \operatorname{argmin}_u \|\widehat{u}\|_{L^1(\mathbb{Z}_N)}$ with the constraint $f(x) = u(x)$ for $x \notin M$. Let $h = f - g$. Then,

$$\frac{1}{|M|} \sum_{x \in M} |h(x)| \leq \frac{2\varepsilon}{N - 2|M||S|} \sum_{x \in \mathbb{Z}_N} |f(x)|. \quad (4)$$

What happens if we send a signal multiple times?

Theorem (Burstein et al '25 [BIMN25])

Let $f : \mathbb{Z}_N \rightarrow \mathbb{C}$, and suppose that f is transmitted but the values $\{f(x)\}_{x \in M}$ are unobserved. Suppose that

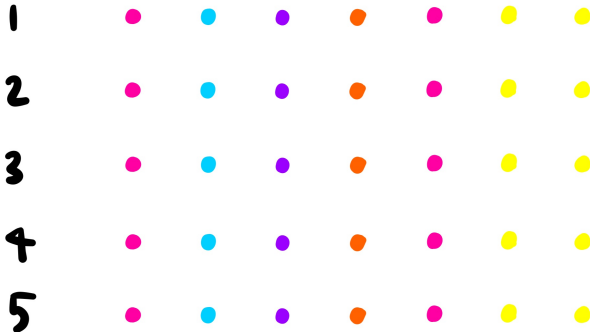
$$\|\widehat{f}\|_{L^1(S^c)} \leq \frac{\varepsilon}{N} \|\widehat{f}\|_{L^1(\mathbb{Z}_N)}. \quad (5)$$

Also suppose that $2|M||S| < N$. Let $g = \operatorname{argmin}_u \|\widehat{u}\|_{L^1(\mathbb{Z}_N)}$ with the constraint $f(x) = u(x)$ for $x \notin M$. Let $h = f - g$. Then,

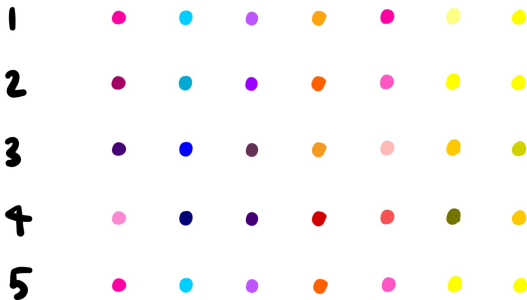
$$\frac{1}{|M|} \sum_{x \in M} |h(x)| \leq \frac{2\varepsilon}{N - 2|M||S|} \sum_{x \in \mathbb{Z}_N} |f(x)|. \quad (6)$$

- Now: use the idea of L^1 -concentration to consider a signal sent multiple times with some noise that makes each iteration of it slightly different.

What happens if we send a signal multiple times?



What happens if we send a signal multiple times?



What happens if we send a signal multiple times?

Definition (Gabor Transform)

Given a function $f : \mathbb{Z}_N \times \mathbb{Z}_T \rightarrow \mathbb{C}$, we define its Gabor Transform $Gf : \mathbb{Z}_N \times \mathbb{Z}_T \rightarrow \mathbb{C}$ by

$$Gf(m, a) := N^{-1/2} \sum_{t \in \mathbb{Z}_N} f(t, a) e^{-2\pi i m \cdot t},$$

i.e., $Gf(m, a) := \widehat{f(\text{---}, a)}(m)$.

We thus have the inverse Gabor transform given by

$$f(t, a) = N^{-1/2} \sum_{m \in \mathbb{Z}_N} Gf(m, a) e^{2\pi i t \cdot m}$$

What happens if we send a signal multiple times?

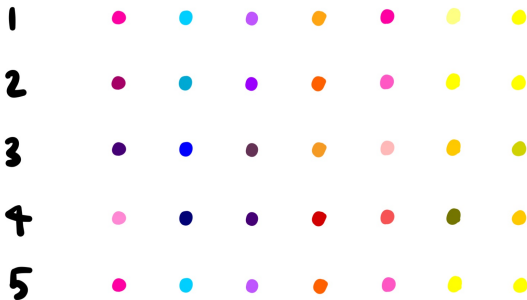
Theorem (SMALL 2025; set-up)

Suppose $f : \mathbb{Z}_N \times \mathbb{Z}_T \rightarrow \mathbb{C}$, we transmit f , the values in $M \times \mathbb{Z}_T$ are unobserved, Gf has support in $S \times \mathbb{Z}_T$, $2|M||S| < N$, and for all $t \notin M$,

$$\sum_{c,b \in A^c} |f(t,c) - f(t,b)| \leq \frac{\varepsilon}{T^2} \sum_{c,b \in \mathbb{Z}_T} |f(t,c) - f(t,b)| \quad (7)$$

where $A \subseteq \mathbb{Z}_T$ and $0 < \varepsilon < 1$.

What happens if we send a signal multiple times?



What happens if we send a signal multiple times?

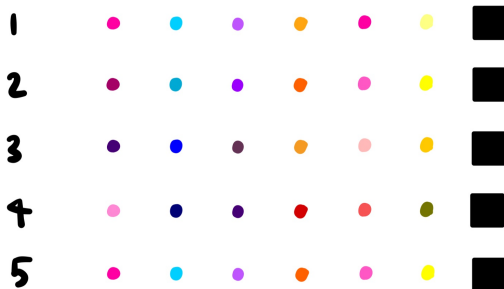
Theorem (SMALL 2025; set-up)

Suppose $f : \mathbb{Z}_N \times \mathbb{Z}_T \rightarrow \mathbb{C}$, we transmit f , the values in $M \times \mathbb{Z}_T$ are unobserved, Gf has support in $S \times \mathbb{Z}_T$, $2|M||S| < N$, and for all $t \notin M$,

$$\sum_{c,b \in A^c} |f(t, c) - f(t, b)| \leq \frac{\varepsilon}{T^2} \sum_{c,b \in \mathbb{Z}_T} |f(t, c) - f(t, b)| \quad (8)$$

where $A \subseteq \mathbb{Z}_T$ and $0 < \varepsilon < 1$.

What happens if we send a signal multiple times?



What happens if we send a signal multiple times?

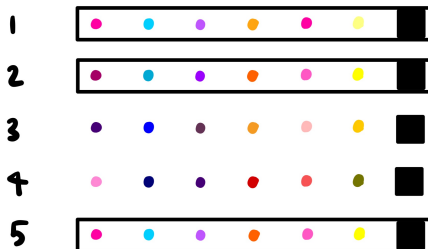
Theorem (SMALL 2025; set-up)

Suppose $f : \mathbb{Z}_N \times \mathbb{Z}_T \rightarrow \mathbb{C}$, we transmit f , the values in $M \times \mathbb{Z}_T$ are unobserved, Gf has support in $S \times \mathbb{Z}_T$, $2|M||S| < N$, and for all $t \notin M$,

$$\sum_{c,b \in A^c} |f(t, c) - f(t, b)| \leq \frac{\varepsilon}{T^2} \sum_{c,b \in \mathbb{Z}_T} |f(t, c) - f(t, b)| \quad (9)$$

where $A \subseteq \mathbb{Z}_T$ and $0 < \varepsilon < 1$.

What happens if we send a signal multiple times?



$$\sum_{c,b \in A^c} |f(t, c) - f(t, b)| \leq \frac{\varepsilon}{T^2} \sum_{c,b \in \mathbb{Z}_T} |f(t, c) - f(t, b)| \quad (10)$$

What happens if we send a signal multiple times?

Theorem (SMALL 2025; continued)

Define $g := \operatorname{argmin}_u \|\widehat{u}\|_{L^1(\mathbb{Z}_N)}$, with the constraint $u(t) = f(t, a)$ for $t \notin M$, where $a \in A^c$ minimizes

$$\sum_{t \in M^c} \sum_{b \in A^c} |f(t, a) - f(t, b)| \quad (11)$$

and let

$$h(t) := \left(\frac{1}{|A^c|} \sum_{b \in A^c} f(t, b) \right) - g(t). \quad (12)$$

Then,

$$\frac{1}{|M|} \|h\|_{L^1(M)} \leq \frac{3\varepsilon|S|}{|A^c|^2 T^2 (N - 2|M||S|)} \sum_{t \in M^c} \sum_{b, c \in \mathbb{Z}_t} |f(t, b) - f(t, c)|. \quad (13)$$

Future Works

Closing



Future Works

- Not requiring exact equality in L^1 -minimization to prevent overfitting.
- Dealing more specifically with general missing value sets.
- Other ways of partitioning $\mathbb{Z}_N \times \mathbb{Z}_T$.

Acknowledgments

- We would like to thank our advisors, Prof. Alex Iosevich and Prof. Eyyvindur Palsson, for suggesting the problems and their mentorship.
- We gratefully acknowledge the support of the National Science Foundation under Grant No. DMS-2241623, as well as the Finnerty Fund. We also thank Princeton University, the University of Cambridge, the University of Wisconsin-Madison, the University of Washington, Williams College, and Yale University.

References I

-  K. Aldahleh, A. Iosevich, J. Iosevich, J. Jaimangal, A. Mayeli, and S. Pack, *Additive energy, uncertainty principle and signal recovery mechanisms*, 2025.
-  Will Burstein, Alex Iosevich, Azita Mayeli, and Hari Sarang Nathan, *Fourier minimization and imputation of time series*, arXiv preprint arXiv:2506.19226 (2025), v1 submitted 24 Jun 2025.

SMALL 2025: Additive Energy Uncertainty Principle

Assume, $|\Sigma| \leq N^{d/3}$ and $|\Sigma| \leq (|E| - 1)^{1/4}$, then if we compare

$$\frac{\sqrt{B_{\Sigma}|E|(\Lambda_2(E) - |E|^2)}}{|\Sigma|} \quad \text{and} \quad \Lambda_2(E) - |E|^2$$

It is the same as comparing

$$B_{\Sigma}|E| \quad \text{and} \quad |\Sigma|^2(\Lambda_2(E) - |E|^2)$$

We know that $B_{\Sigma} = |\Sigma - \Sigma| |(\Sigma + \Sigma) - (\Sigma + \Sigma)| \leq |\Sigma|^6$. We also know that $\Lambda_2(E) - |E|^2 \geq |E|^2 - |E|$, so

$$B_{\Sigma}|E| \leq |\Sigma|^6|E| \leq |\Sigma|^2|E||\Sigma|^4 \leq |\Sigma|^2(\Lambda_2(E) - |E|^2)$$

Hence, the second inequality is stronger than the first one.