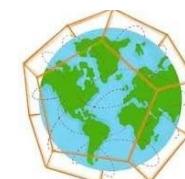


# From Alligators to All In - Generalized Predator-Prey Problems and Guided Online Research

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with  
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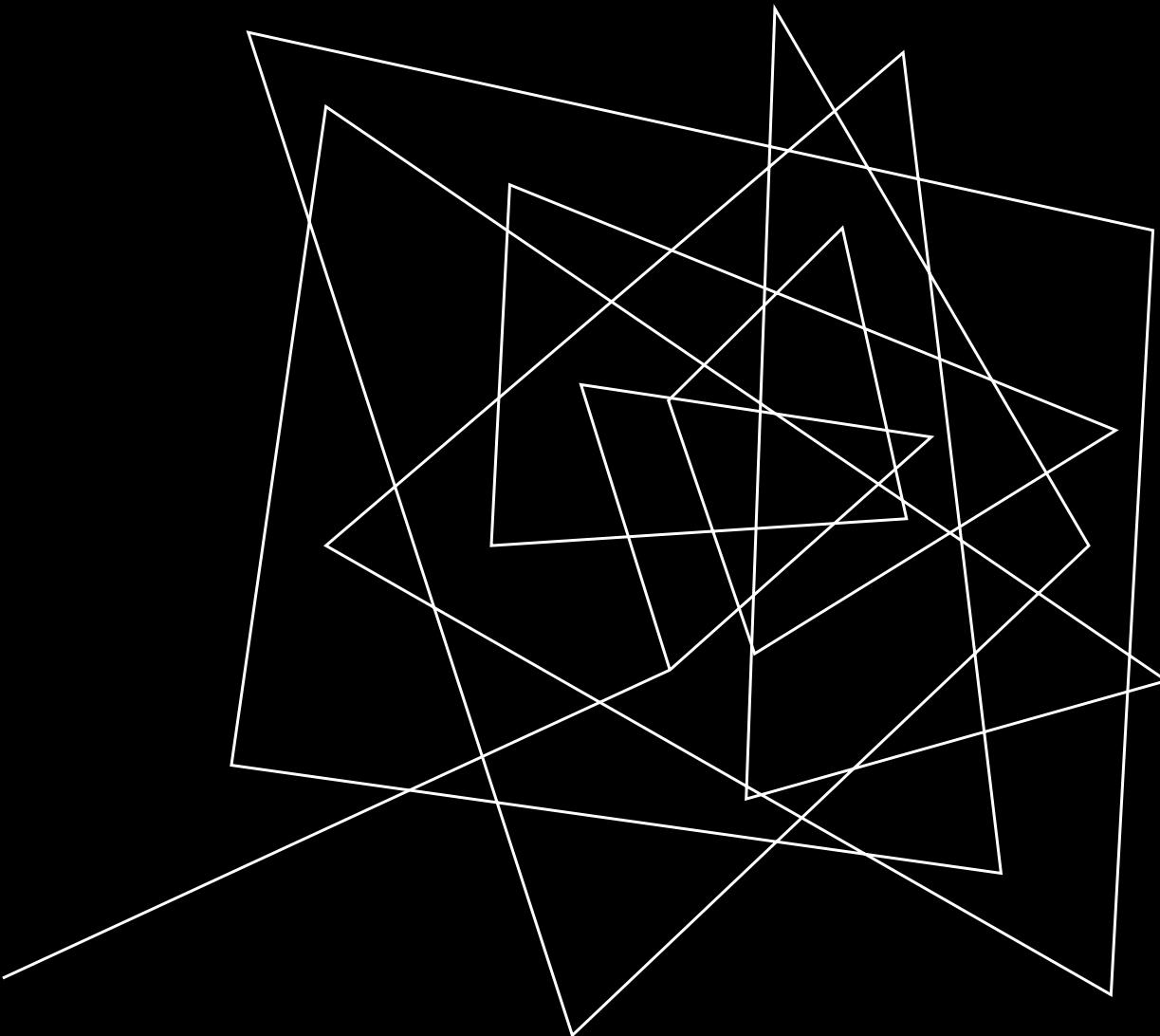
**SIMIODE EXPO 2026, Saturday, February 14, 2026**



[https://web.williams.edu/Mathematics/sjmiller/public\\_html/math/talks/talks.html](https://web.williams.edu/Mathematics/sjmiller/public_html/math/talks/talks.html)

Supported in part by NSF Grant number: DMS2341670

# Sections



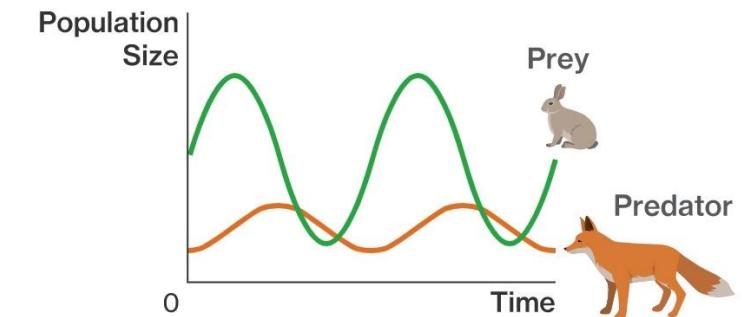
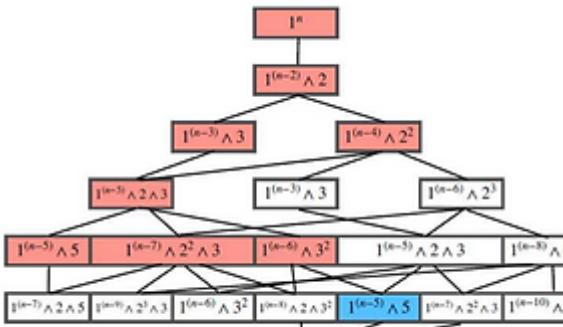
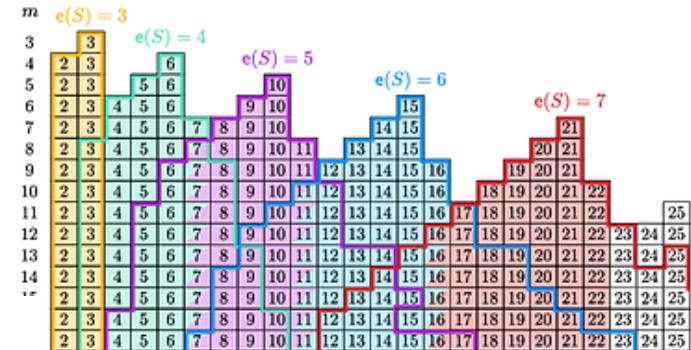
- 1) Polymath Jr.
- 2) Know your team
- 3) Research that makes a difference
- 4) PP models and how to approach
- 5) Results, Collaborations, future steps, and lessons learned

# Polymath Jr.

Our goal is to provide research opportunities to every undergraduate who wishes to explore advanced mathematics.

Each project is mentored by an active researcher with experience in undergraduate mentoring.

<https://geometrnyc.wixsite.com/polymathreu>



## How Polymath Works

- 1) Polymath accepts hundreds of applications every year, with priority given to seniors.
- 2) All students attend a series of online sessions that introduce a wide range of topics and provide insight into potential projects.
- 3) Mentors receive training on handling stressful situations, leading effectively, giving students space, motivating them, and more.
- 4) Each graduate mentor is paired with a faculty supervisor who guides and oversees the project.
- 5) After these sessions, students choose their top three projects. Students are then matched with a mentor and a supervisor.



# Meet the Team



Anh Quynh Bui



Jasmine Pham



Jessie Wang



Sangam Dhakal

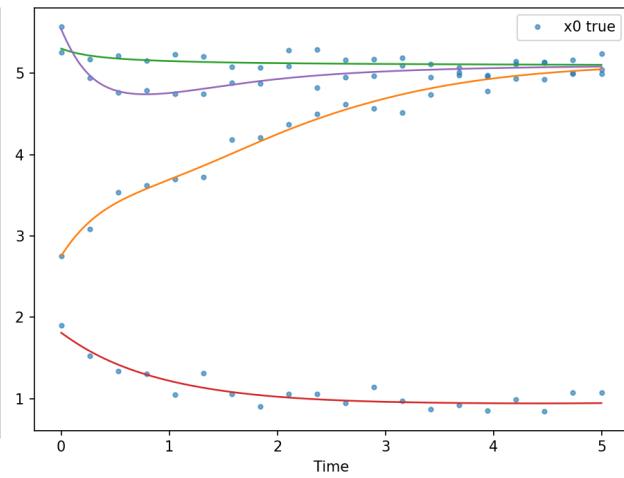
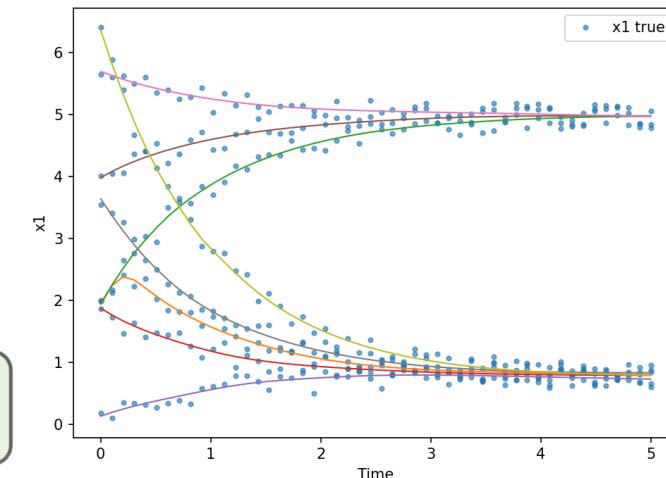
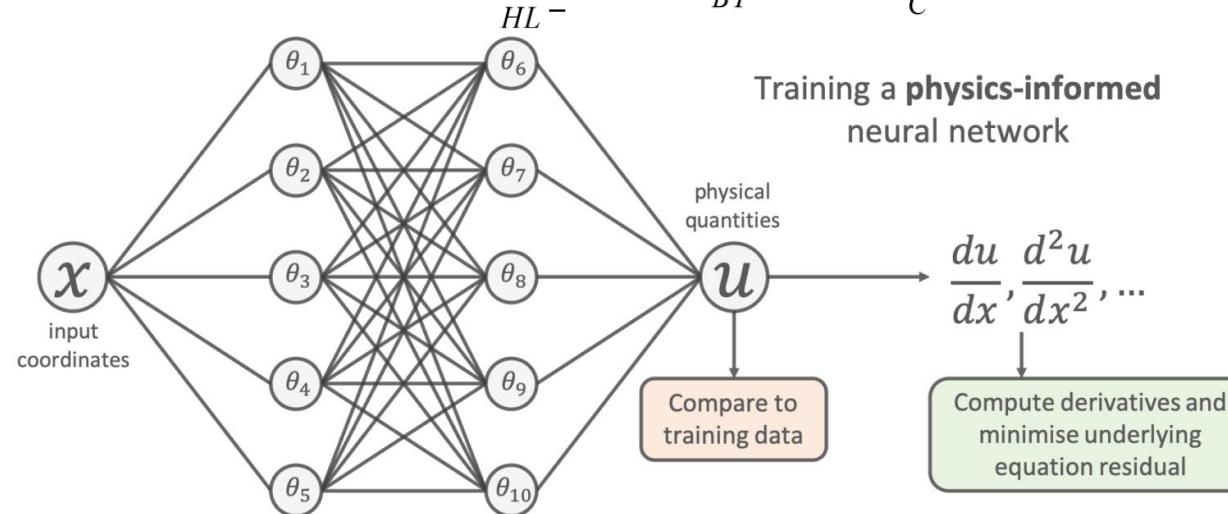
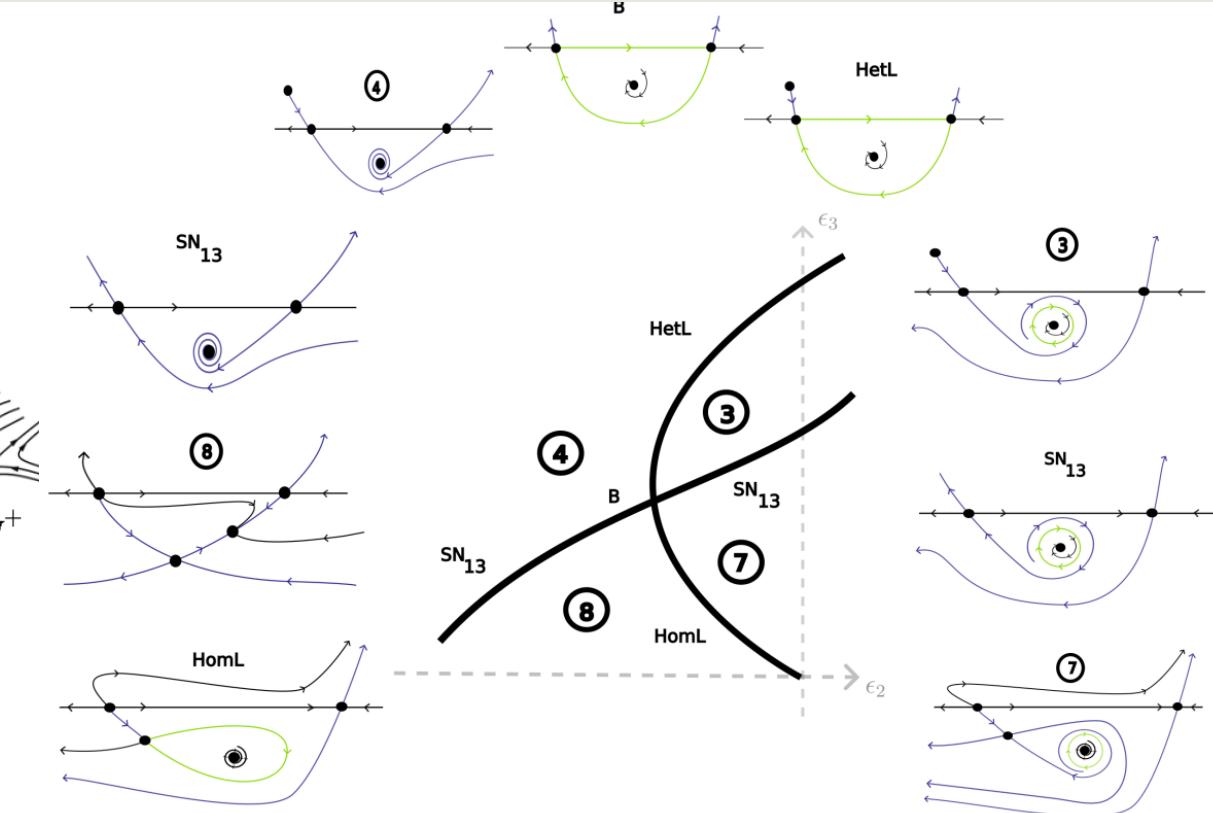
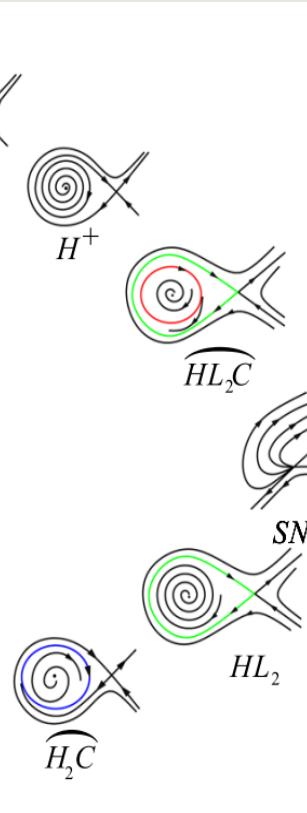
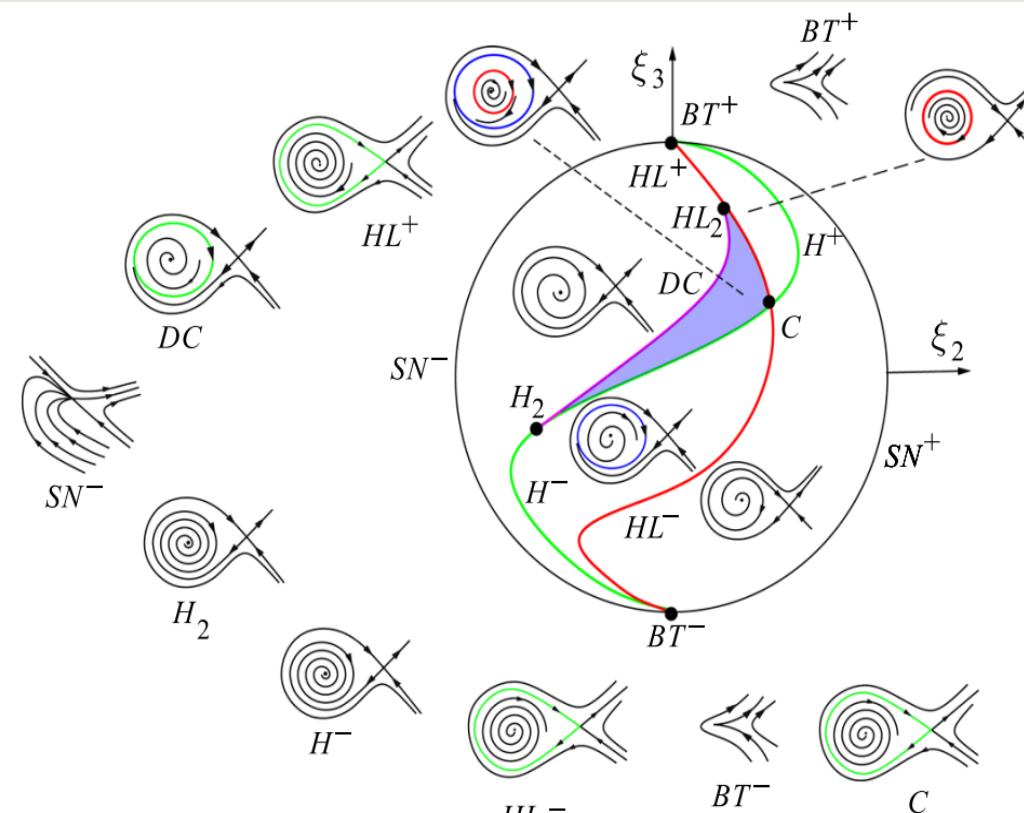


Steven Miller



Wael El Khateeb

# My Background



## PHASE 1: Introduction

How to guide students without prior differential equations experience to produce high-quality research in just six weeks?

We established a clear framework built on the following principles.

### Consistent and Timely Communication

- The average email response time, amazingly, did not exceed 30 minutes.

### Restricted Material

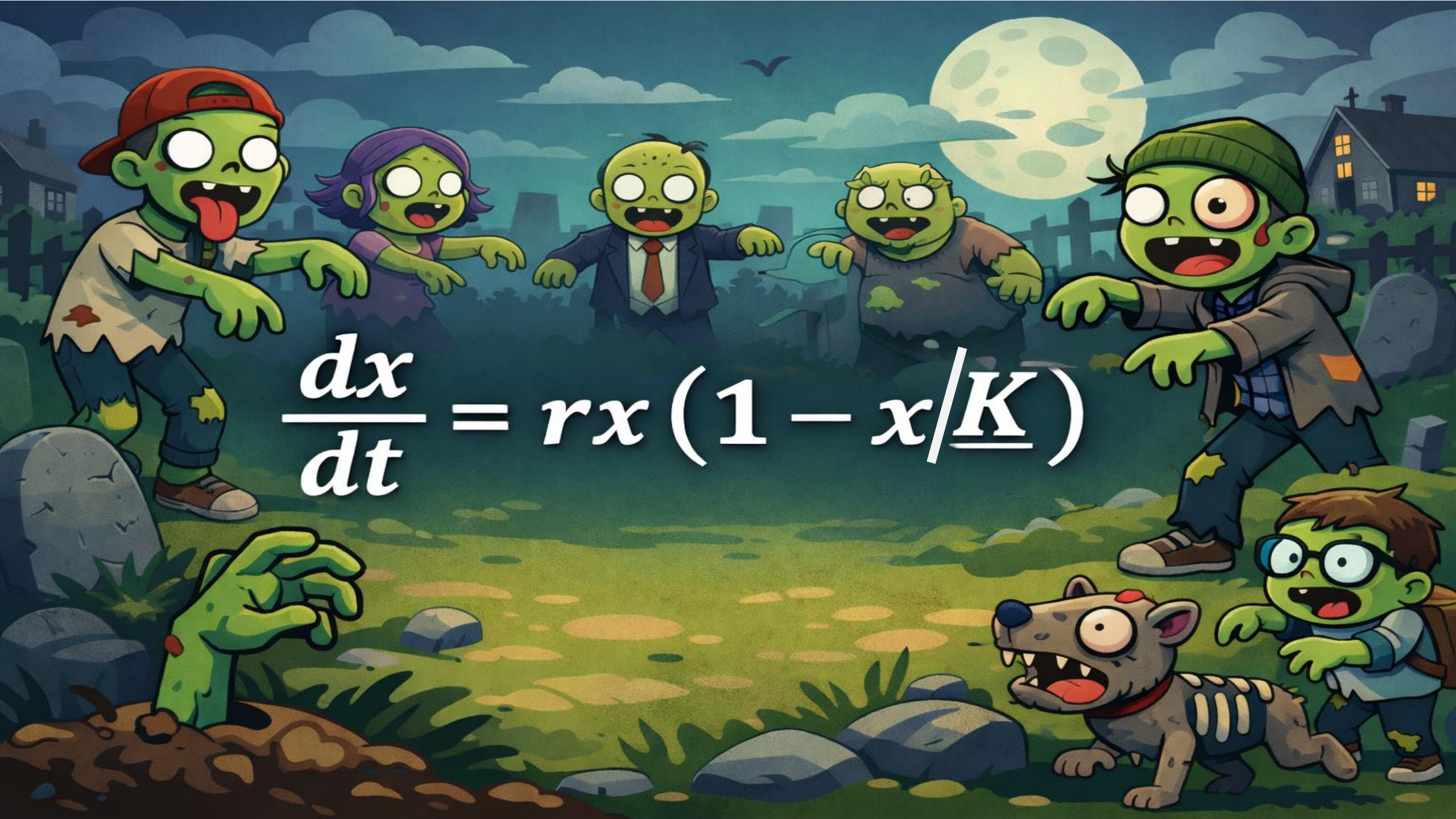
- Restricting our sharing of knowledge to only the essential tools (System of ODEs, Jacobian, basic bifurcations,...).

### Weekly group meetings

- Complemented by one-on-one office hours.

### Positive Reinforcement and motivation

- Maintain high morale throughout the program to encourage confidence and sustained engagement.
- Motivating goal: All expense paid trip to UT Austin to present at a research conference.

A cartoon illustration of a zombie apocalypse at night. In the foreground, a zombie with a red baseball cap and a torn shirt is on the left, and a zombie with purple hair and a torn dress is behind it. In the center, a zombie in a suit and tie is walking. On the right, a zombie in a grey jacket and blue pants is walking. In the bottom right corner, a zombie with glasses and a backpack is walking next to a zombie dog. The background features a large, cratered moon in a dark blue sky with white clouds. In the distance, there are buildings and a city skyline. The ground is green with some brown spots and rocks.
$$\frac{dx}{dt} = rx(1 - x/\underline{K})$$

Find the values of the functions

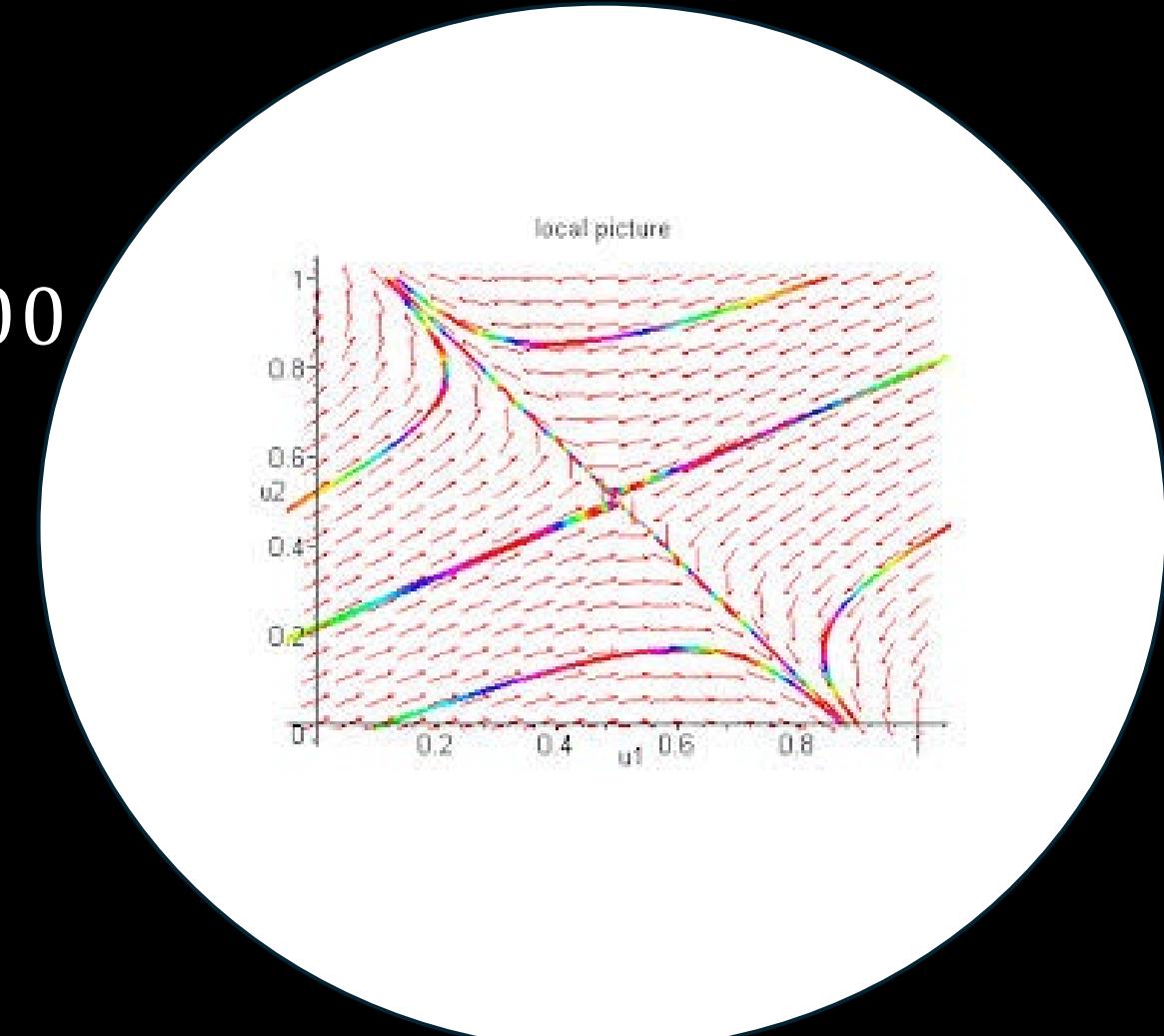
$$f_1(x) = x, f_2(x) = x^2, f_3(x) = x^3$$

near  $x = 100, x = 1000, x = 10000$

Now do the same for

$x = 0.01, x = 0.001, x = 0.0001$

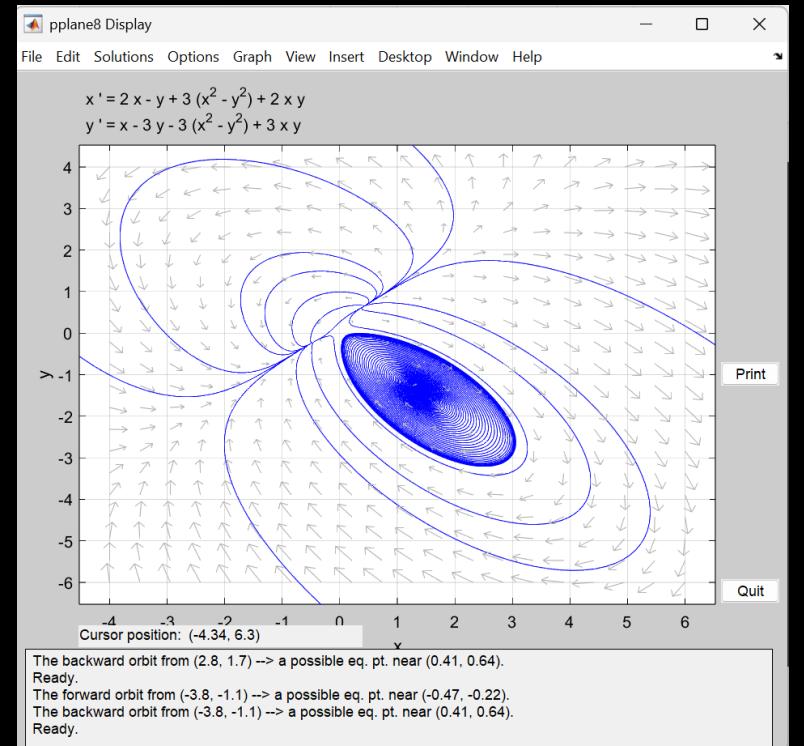
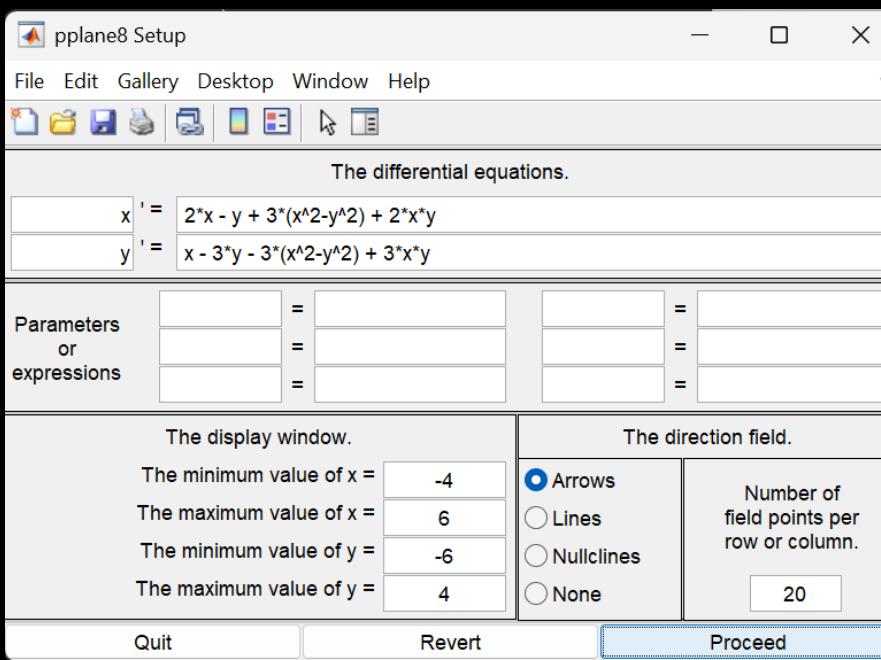
What can you conclude?



# Software tools

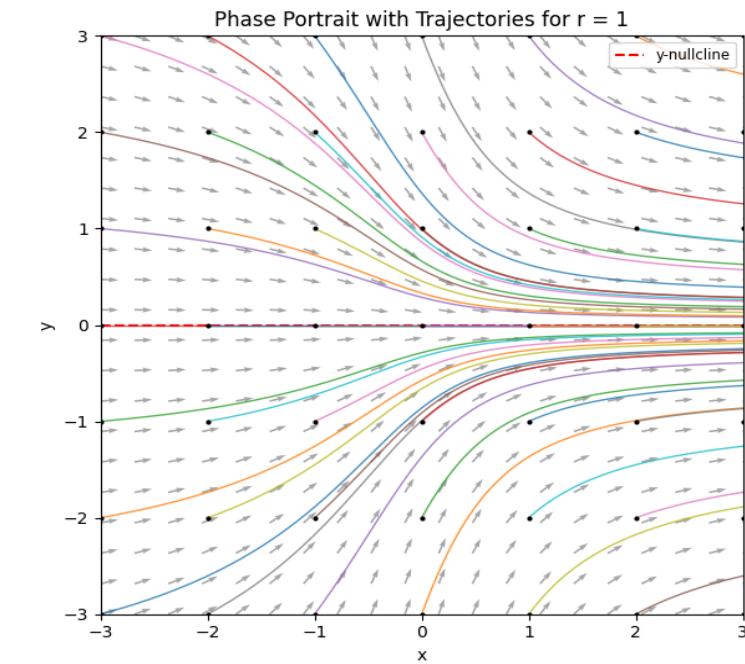
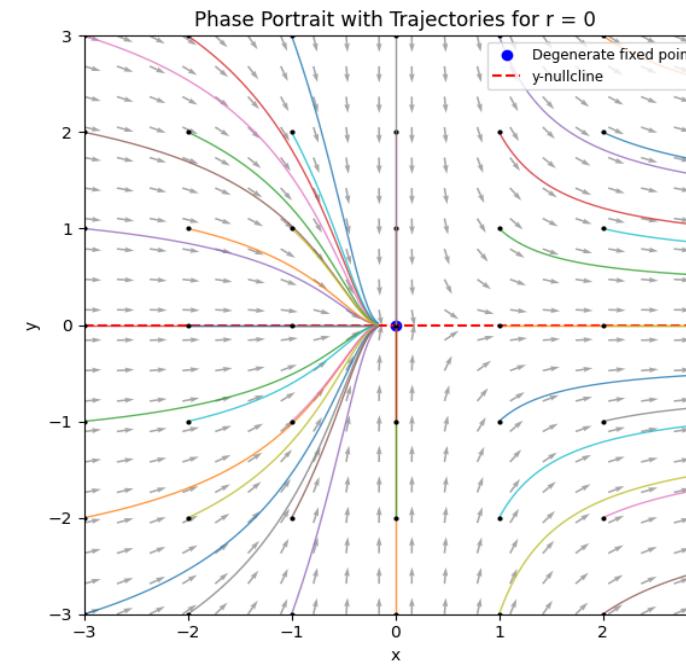
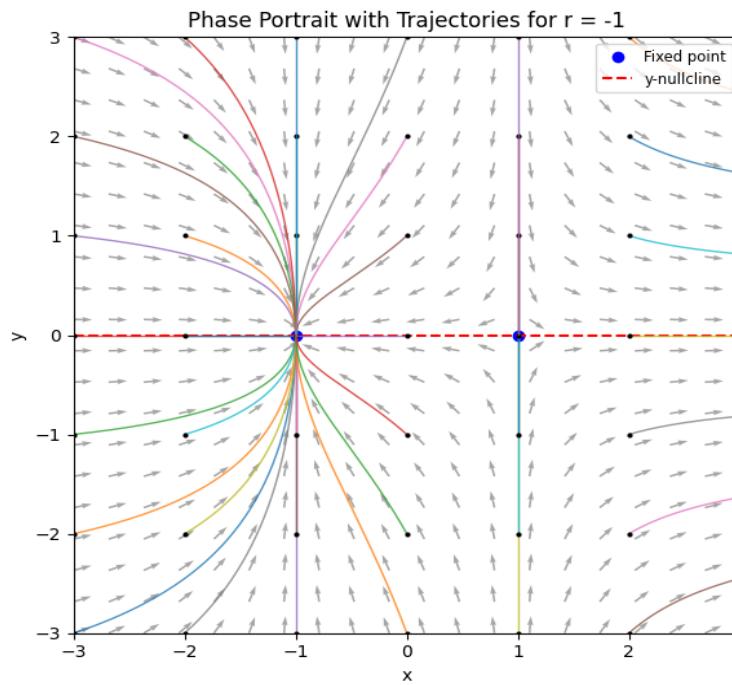
- 1) pplane
- 2) ODE 45

Well written code that students read, analyze, understand, and use instead of writing from scratch.



# Bifurcations: qualitative change in the behavior of a system as a parameter is varied.

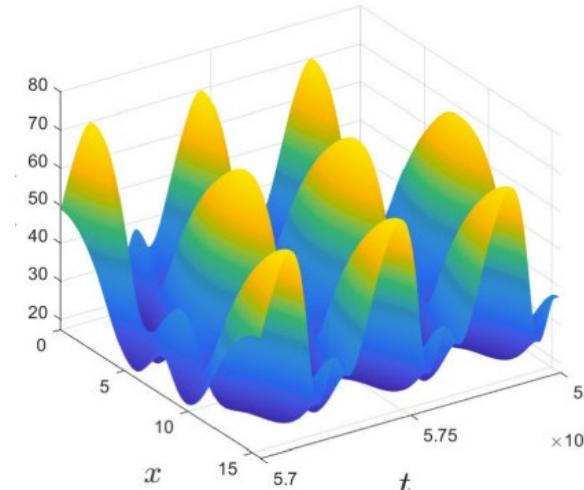
$$\begin{cases} \frac{dx}{dt} = r + x^2, \\ \frac{dy}{dt} = -y. \end{cases}$$



# HOW TO KEEP STUDENTS ON TRACK? WHAT IF STUDENTS WERE NOT PREPARED?

Think-Pair-Share  
Slide preparation on the spot

$$\begin{aligned} S_t - r_1 \Delta S &= A - dS - \beta SI, \\ I_t - r_2 \Delta I &= \beta SI - dI - h(I)I, \\ R_t - r_3 \Delta R &= h(I)I - dR, \end{aligned}$$



$$\begin{cases} \frac{dx(t)}{dt} = rx(t) \left(1 - \frac{x(t)}{K}\right) - \frac{mx(t)y(t)}{a + x(t)}, \\ \frac{dy(t)}{dt} = -dy(t) + e^{-d\tau} \frac{cmx(t - \tau)y(t - \tau)}{a + x(t - \tau)}, \end{cases}$$

Initial condition is a trajectory!



## BACKGROUND (BIOLOGY)

1800s to mid-1900s: Intense hunting for leather and meat.

1950s to 1960s: Populations crash; poaching persists; weak enforcement.

1967: Listed as endangered in the United States.

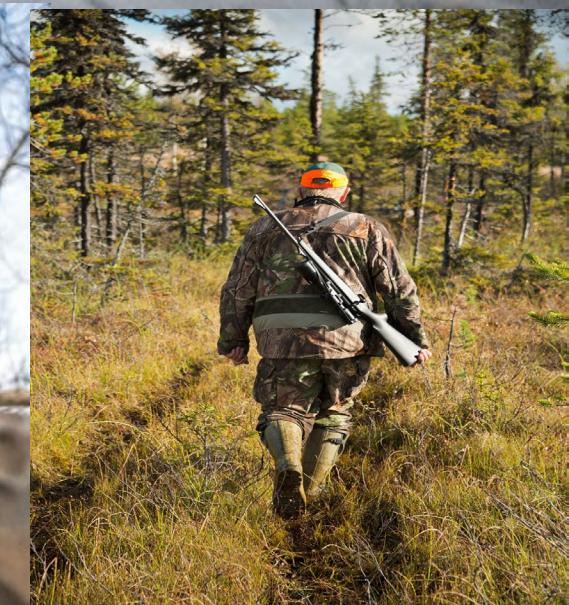
1970s: States close hunting, protect nests, begin science-based management.

## BACKGROUND (BIOLOGY)

Late 1970s to 1980s: Rebound via protection, anti-poaching, wetland conservation.

1987: Delisted federally; managed as “threatened due to similarity of appearance.”

FWC lottery permits; two alligators per permit.



VICELAND

# Burmese Pythons



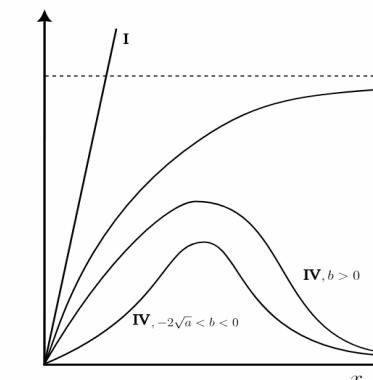
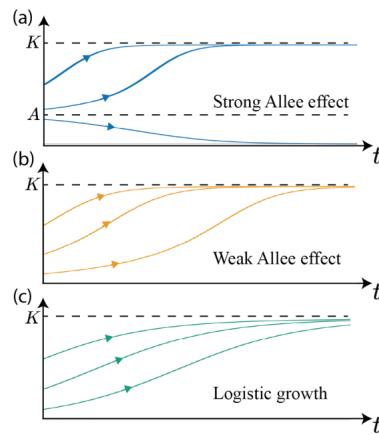
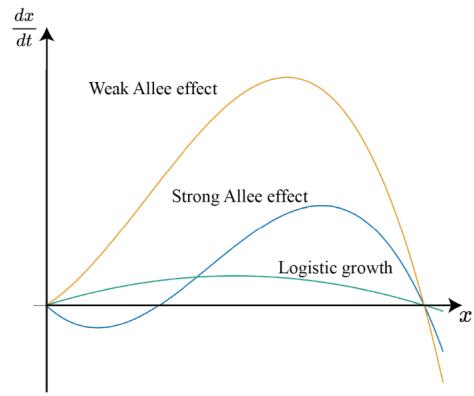
- Intentional releases by owners who could no longer keep large snakes.
- Accidental escapes from pet stores, breeders, and private collections.
- Facility damage during Hurricane Andrew (1992) likely released additional snakes into the Everglades.

# ECOLOGICAL IMPLICATIONS

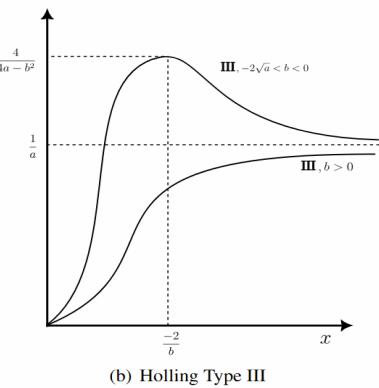
- Sharp declines of midsized mammals in parts of the Everglades (raccoons, opossums, marsh rabbits)
- Competition with native apex predators for prey, altering food webs



# PP model and extensions



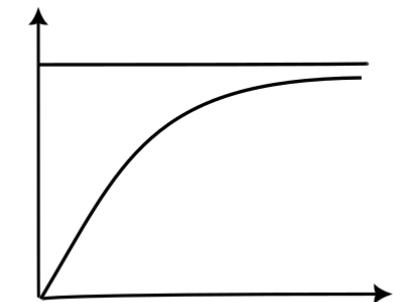
(a) Holling Type I,II, and IV



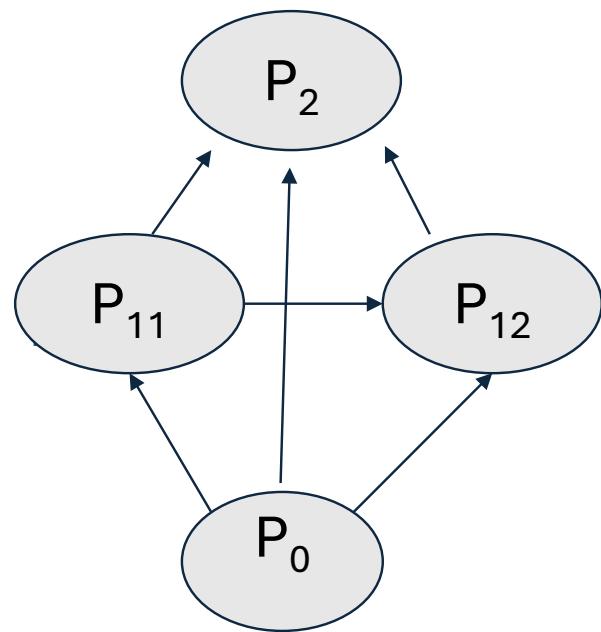
(b) Holling Type III

$$\frac{dx}{dt} = G_1(x) - \alpha_1 F(x)y - H_1(x)$$

$$\frac{dy}{dt} = -G_2(y) + \alpha_2 F(x)y - H_2(y)$$



## Model Illustrated:



$P_0$  - Raccoon/prey population

$P_{11}$  - Juvenile Alligator population

$P_{12}$  - Adult Alligator population

$P_2$  - Burmese Python population

## Initial Model

$$\begin{cases} \frac{dP_0}{dt} = rP_0 - m_{20}P_0P_2 - m_{30}P_0P_2 \\ \frac{dP_1}{dt} = c_{20}P_0P_2 - m_{31}P_1P_3 - d_{11}P_{11} \\ \frac{dP_2}{dt} = d_{12}P_1 - d_2P_2 - h_2 \\ \frac{dP_3}{dt} = c_{30}P_0P_3 + c_{31}P_3P_1 - d_3P_2 - h_3P_2 \end{cases}$$

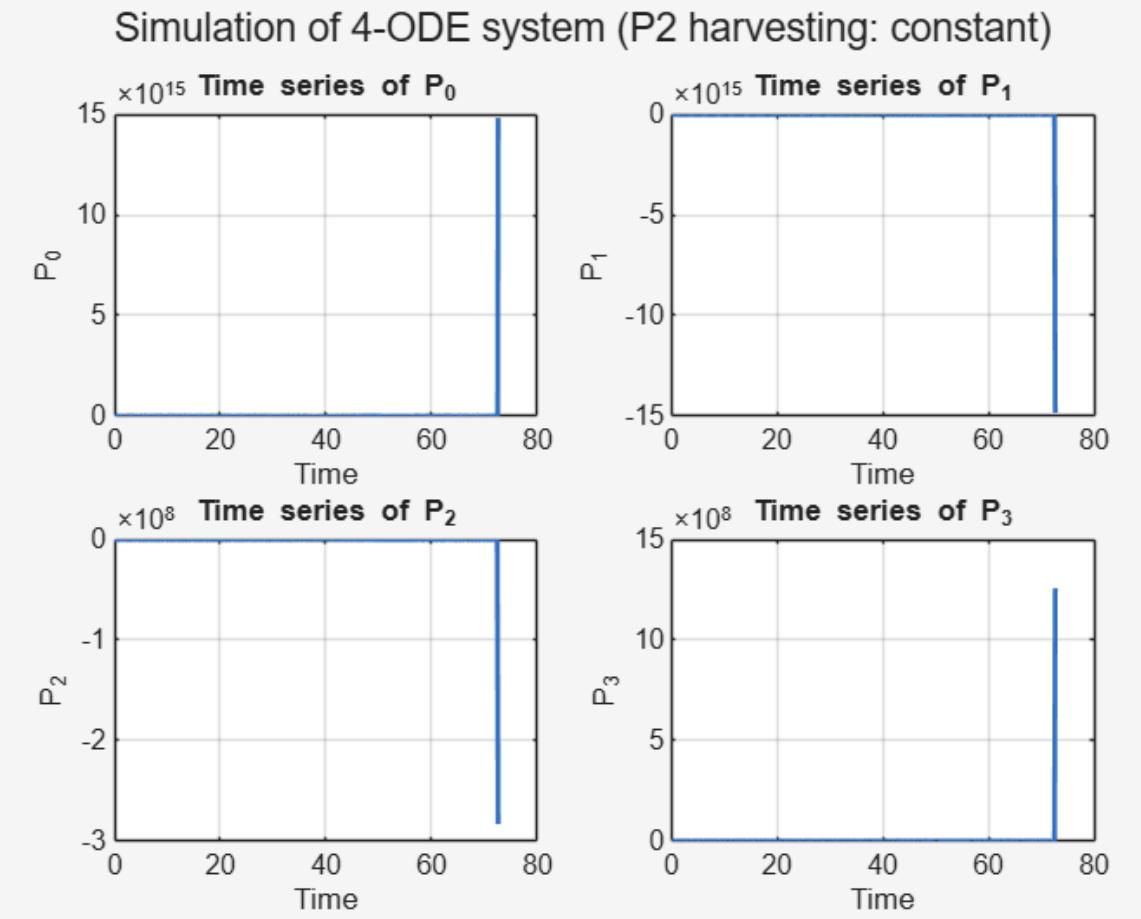
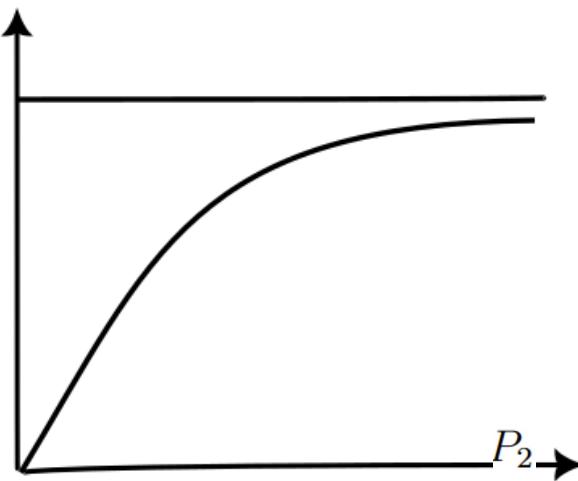
$h_2 \Rightarrow \text{Saturated}$



$$\begin{cases} \frac{dP_0}{dt} = rP_0 - m_{20}P_0P_{12} - m_{30}P_0P_2 \\ \frac{dP_{11}}{dt} = c_{20}P_0P_{12} - m_{31}P_{11}P_3 - d_{11}P_{11} \\ \frac{dP_{12}}{dt} = d_{12}P_{11} - d_2P_{12} - h_2 \frac{P_{12}}{a + P_{12}} \\ \frac{dP_2}{dt} = c_{30}P_0P_2 + c_{31}P_2P_{11} - d_3P_2 - h_3P_2 \end{cases}$$

# Why constant harvesting doesn't work

Applying constant harvesting shows that  $P_1$  and  $P_2$  eventually become **negative**, which is biologically unrealistic and highlights why **constant harvesting does not work**.



# Final Model

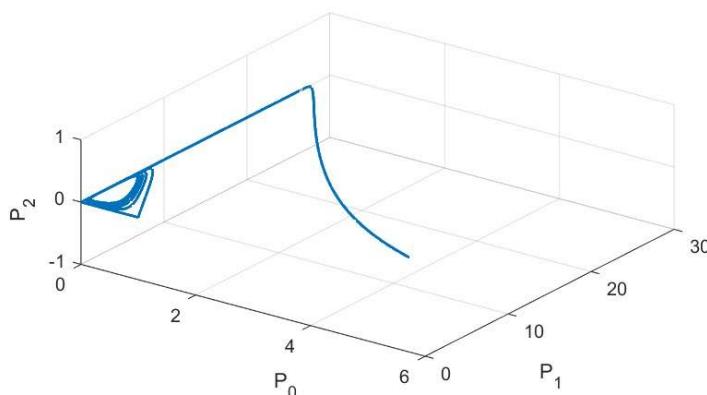
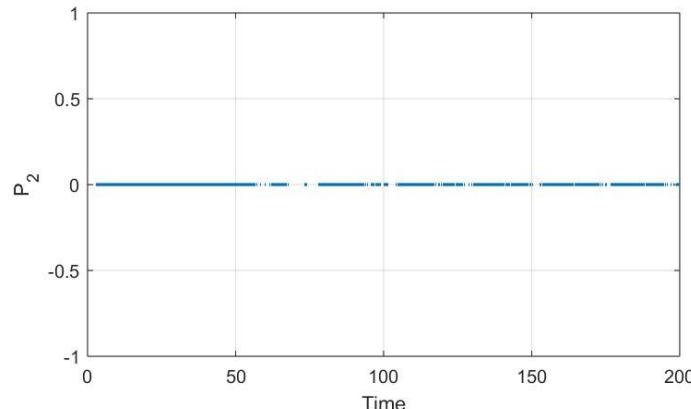
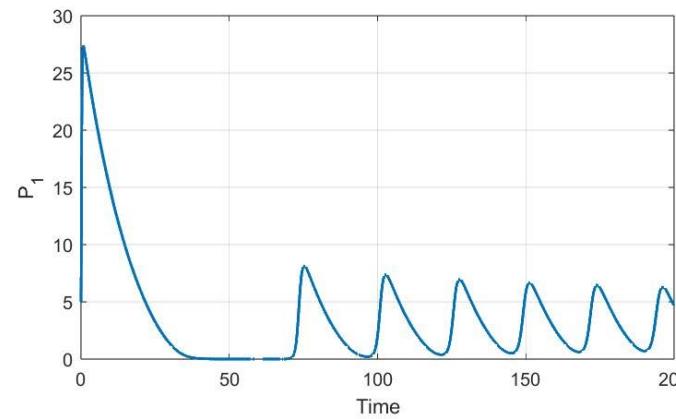
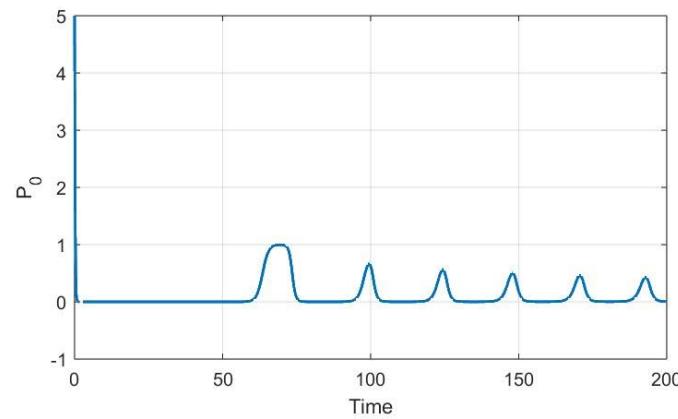
$$\begin{cases} \frac{dP_0}{dt} = rP_0 \left(1 - \frac{P_0}{K}\right) - m_{10}P_0P_1 - m_{20}P_0P_2, \\ \frac{dP_1}{dt} = c_{10}P_0P_1 - d_1P_1 - \frac{h_1P_1}{a + P_1} - m_{31}P_1P_2, \\ \frac{dP_2}{dt} = c_{20}P_0P_2 + c_{21}P_1P_2 - d_2P_2 - h_2P_2. \end{cases}$$

## Equilibria: 7 in total

- 2 Equilibria on the  $P_0$  axis.
- 2 equilibria on the  $P_0 - P_1$  plane suggesting that the prey can coexist with the alligators.
- 2 non-zero equilibria where all 3 species coexist.
- 1 equilibrium in the  $P_0 - P_2$  plane suggesting that python can coexist with the general prey.

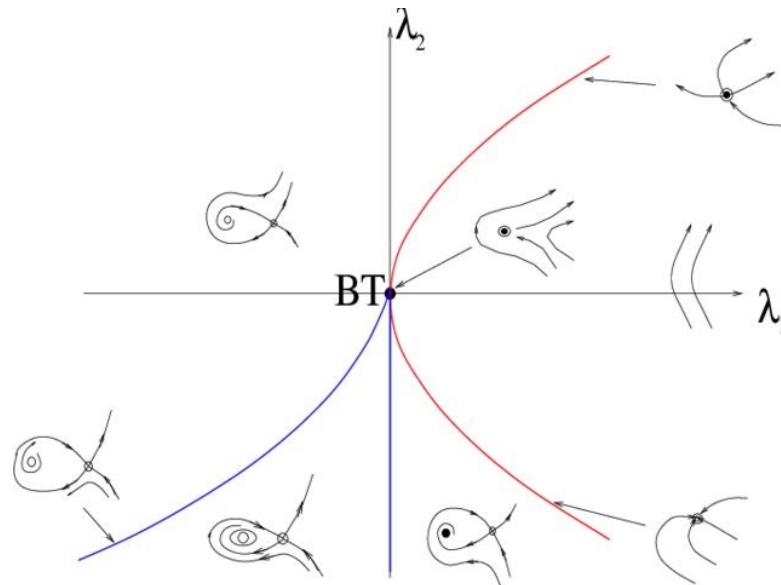
## THE CASE WITH NO BURMESE PYTHONS

- The system provides grounds to modeling the relation between Alligators and general prey in the absence of pythons.



What happens if both Hopf and Saddle node occur simultaneously?

Students were able to do so using Bogdanov takens bifurcations, which explained to formation of limit cycles



1. **Shift the equilibrium:** Find the equilibrium  $P^* = (P_0^*, P_1^*, P_2^*)$  and shift variables:

$$u = P_0 - P_0^*, \quad v = P_1 - P_1^*, \quad w = P_2 - P_2^*$$

so that the system becomes  $\dot{z} = F(z)$  with  $F(0) = 0$ .

2. **Linearize and identify eigen-directions:** Compute the Jacobian  $J = DF(0)$ . At the BT point:  $\text{spec}(J) = \{0, 0, \lambda_s\}$  with  $\lambda_s < 0$ . The eigenvectors corresponding to zero eigenvalues define the center subspace.

3. **Center manifold reduction (3D  $\rightarrow$  2D):** There exists a smooth invariant manifold  $w = h(u, v)$  with  $h(0) = 0, Dh(0) = 0$ . Substituting  $w = h(u, v)$  reduces the system to:

$$\dot{u} = \tilde{F}_1(u, v), \quad \dot{v} = \tilde{F}_2(u, v)$$

4. **Reduced dynamics:** Expand  $\tilde{F}_1, \tilde{F}_2$  in a Taylor series near the origin and retain quadratic terms:

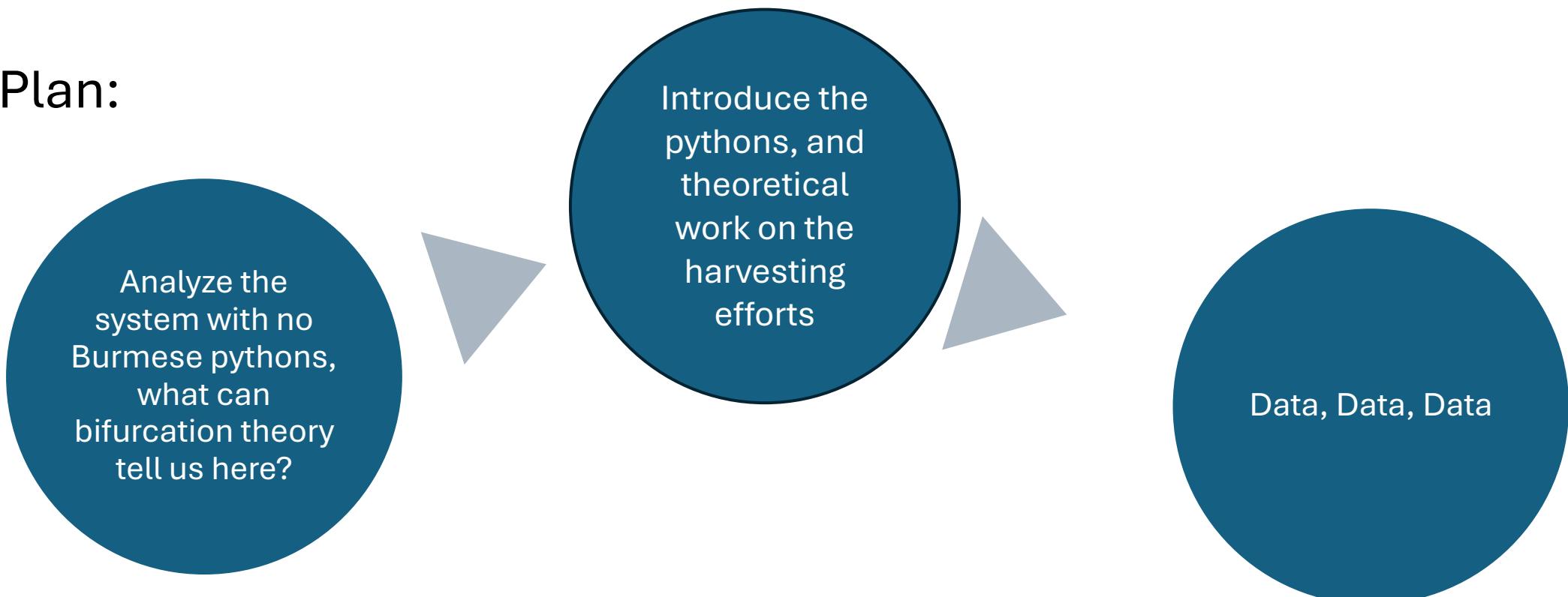
$$\dot{u} = v + \mathcal{O}(2), \quad \dot{v} = au^2 + buv + \dots$$

5. **Transform to BT normal form:** Apply smooth coordinate and parameter changes to obtain:

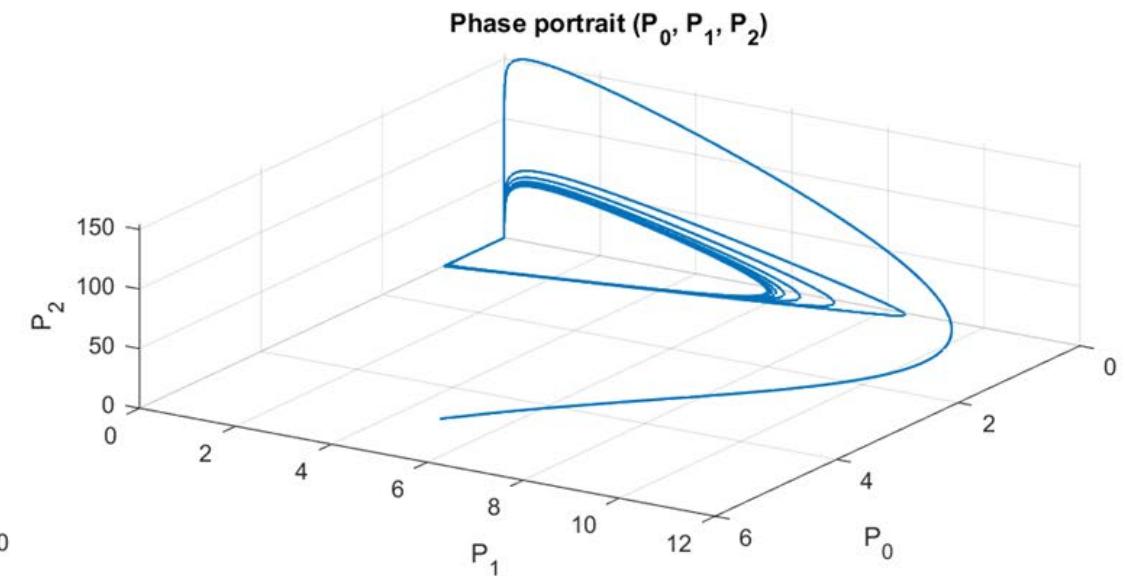
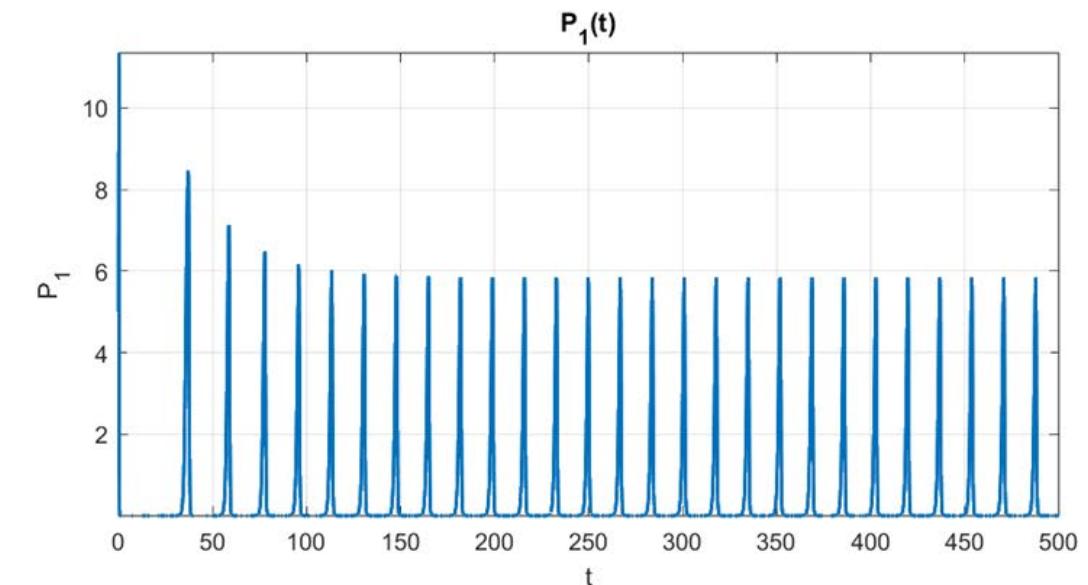
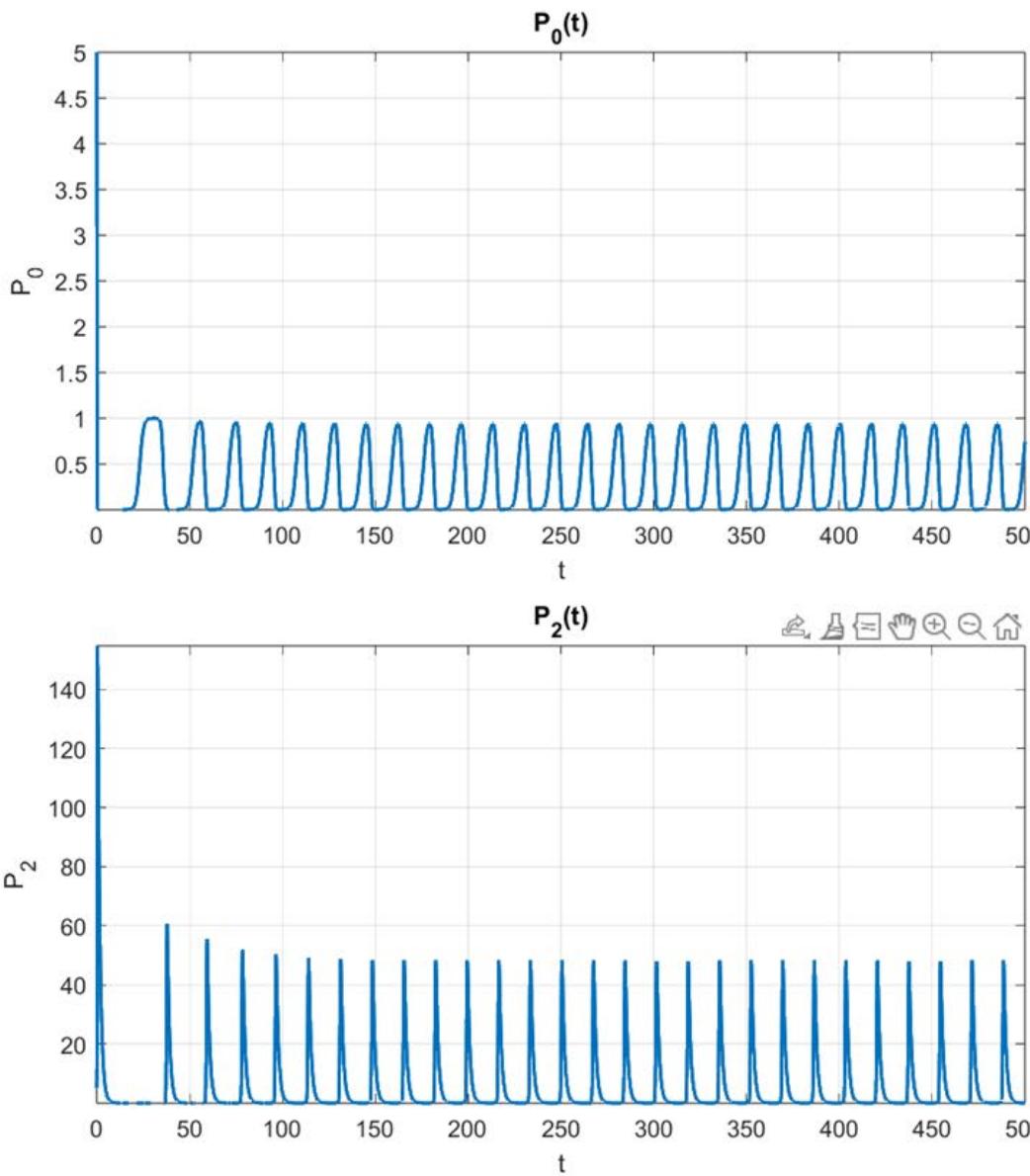
$$\dot{x} = y, \quad \dot{y} = \beta_1 + \beta_2 x + ax^2 + bxy + \mathcal{O}(3)$$

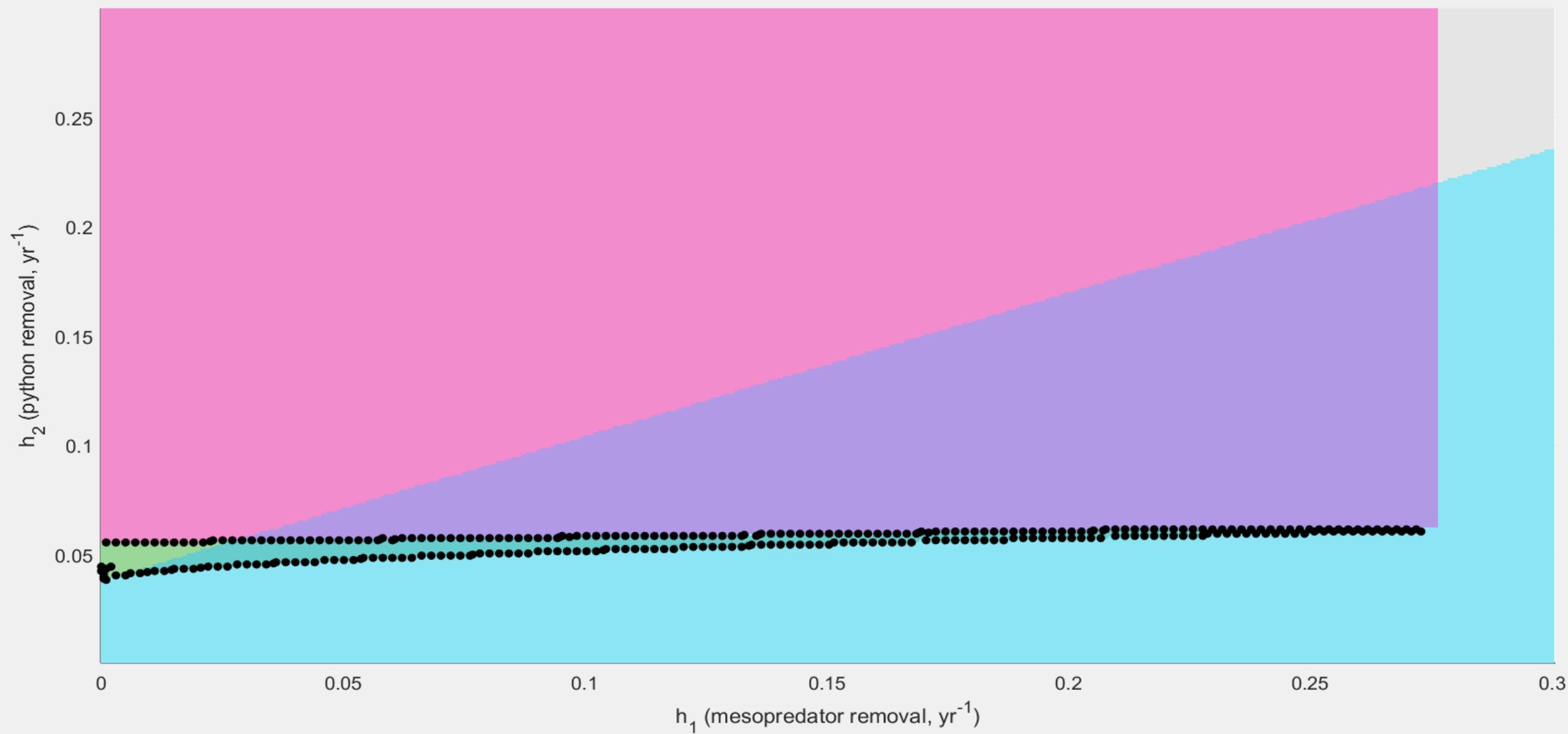
# Ultimate goal: Policy making

- With current harvesting restricted to 2 alligators per hunter, per season, should the hunting policies be altered, especially that the common prey population is decreasing (Racoons drop by 95%...)
- Plan:



# The presence of Burmese Pythons





Both Alligators and Pythons go extinct  
Alligators and Prey can only coexist  
Pythons and Prey can only coexist  
Pythons and Alligators can coexist with Prey, but not with one another  
Pythons and Alligators can only coexist at the same time

Alligators and Prey can coexist without Pythons, and all three can coexist simultaneously  
Pythons and Prey can coexist without Alligators, and all three can coexist simultaneously  
Pythons and Prey can coexist, Alligators and prey can coexist, all three can coexist simultaneously  
● coexistence stability boundary

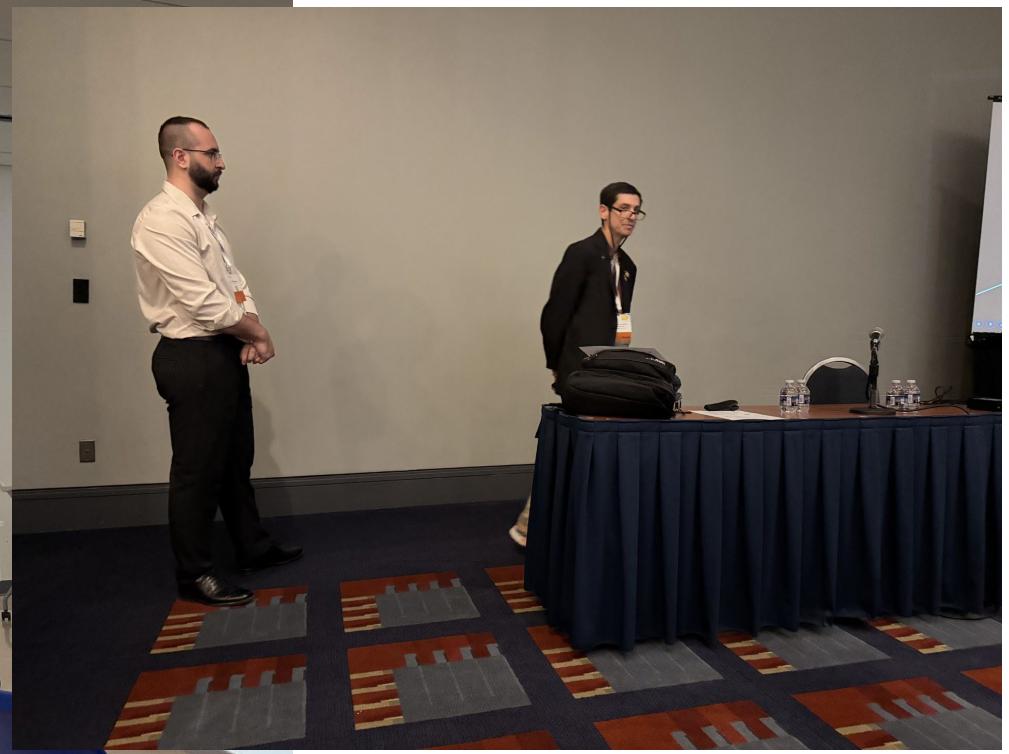


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# SIAM TX-LA Conference and JMM 2026





## Useful techniques/ Strategies implemented

- **Ownership**
- **Reaching out to contacts**
- **Know your strong points,  
know your weak points**
- **Always have something  
to share**
- **Provide opportunities,  
but students must seize**

Thank you!

Steven J Miller  
Professor  
Williams College



Wael El Khateeb  
Ph.D. Candidate in Applied Math  
The University of Toledo



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Personal Webpage