

# MATH 211 HOMEWORK 9 SOLUTIONS ①

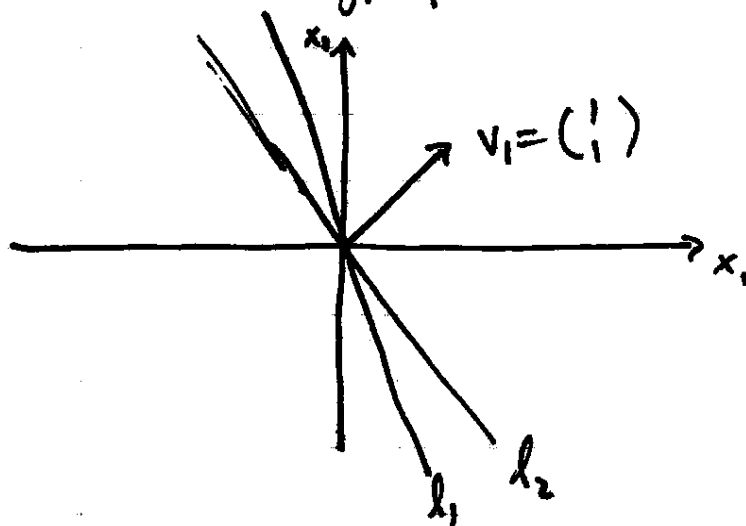
① The orthogonal set to  $v_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$  is

$$\begin{aligned} v_1^\perp &= \left\{ x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid (1 \ 1) \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \right\} \\ &= \left\{ x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid 3x_1 + 2x_2 = 0 \right\} = \ell_1 \end{aligned}$$

For the dot product, the set orthogonal to  $v_1$  is

$$\begin{aligned} v_1^\perp &= \left\{ x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} \mid (1 \ 1) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \right\} \\ &= \left\{ x \mid x_1 + x_2 = 0 \right\} = \ell_2 \end{aligned}$$

These are both hyperplanes in  $\mathbb{R}^2$ :



For  $v_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ , we perform similar computations to find for the new inner product

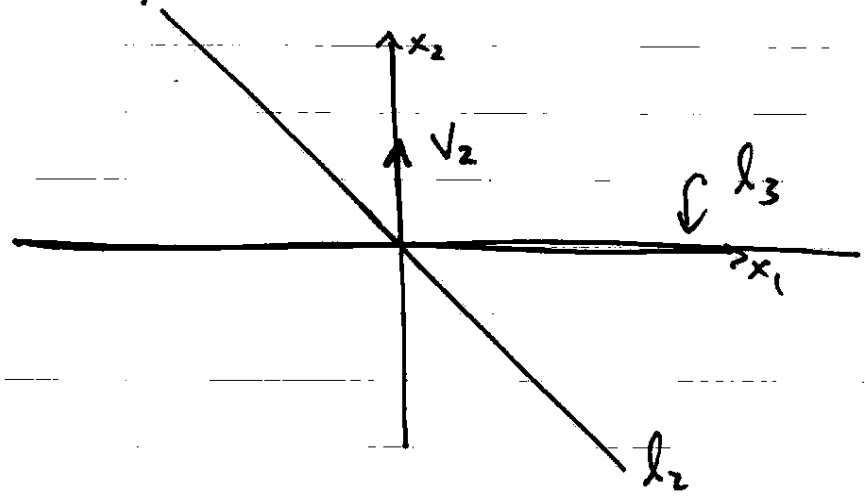
$$v_2^\perp = \left\{ x \mid (0 \ 1) \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \right\} = \ell_2 \text{ from above!}$$

and for the dot product

$$v_2^\perp = \left\{ x \mid (0 \ 1) \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = 0 \right\} = \left\{ x \mid x_2 = 0 \right\} = \text{x-axis!} \\ = \ell_3$$

① (cont.)

So our picture is



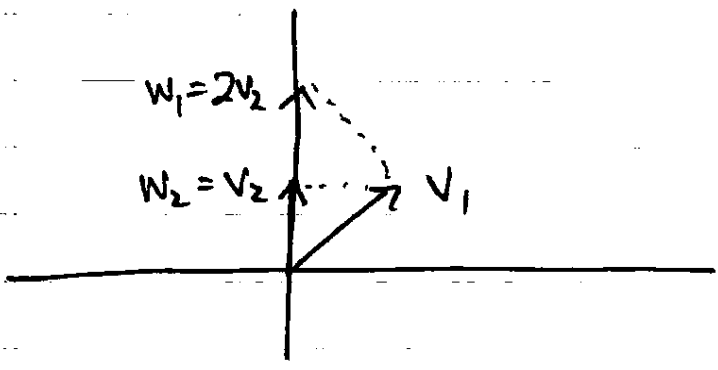
We can see from these pictures that the notions of orthogonal are quite different for these inner products.

For the new inner product, we compute

$$w_1 = Pr_{v_2}(v_1) = \frac{\langle v_1, v_2 \rangle}{\langle v_2, v_2 \rangle} v_2 = \frac{2}{1} v_2 = 2v_2$$

For the dot product

$$w_2 = Pr_{v_2}(v_1) = \frac{\langle v_1, v_2 \rangle}{\langle v_2, v_2 \rangle} v_2 = \frac{1}{1} v_2 = v_2$$



These projections are quite different!

$$\textcircled{2} \text{ (1) } \operatorname{tr}(A) = 5 + (-4) + (-3) = -2$$

$$\operatorname{tr}(B) = 4 + 3 + 1 + 2 = 10$$

(2) The matrices  $X$  and  $X^t$  have the same diagonal entries, so  $\operatorname{tr}(X) = \operatorname{tr}(X^t)$

(3) Let  $A = (a_{ij})$  and  $B = (b_{ij})$  be  $n \times n$  matrices and let  $\alpha, \beta \in \mathbb{R}$ . Then we have

$$\begin{aligned} \operatorname{tr}(\alpha A + \beta B) &= \operatorname{tr}(\alpha a_{ij} + \beta b_{ij}) = \sum_{i=1}^n (\alpha a_{ii} + \beta b_{ii}) \\ &= \alpha \sum_{i=1}^n a_{ii} + \beta \sum_{i=1}^n b_{ii} = \alpha \operatorname{tr}(A) + \beta \operatorname{tr}(B) \end{aligned}$$

Therefore,  $\operatorname{tr} : M_{nn}(\mathbb{R}) \rightarrow \mathbb{R}$  is a linear transformation.

(3) To see that the trace form defines an inner product we must check 3 properties:

(1) Symmetry, (2) bilinearity, (3) Positive definiteness  
We take these in order:

(1) By exercise 2,  $\operatorname{tr}(X) = \operatorname{tr}(X^t)$ . Note that  $A^t B = (B^t A)^t$ . Thus

$$\langle A, B \rangle = \operatorname{tr}(B^t A) = \operatorname{tr}(A^t B) = \langle B, A \rangle.$$

(2) Since  $\operatorname{tr}$  is a linear transformation, we have

$$\begin{aligned} \langle \alpha A_1 + \beta A_2, B \rangle &= \operatorname{tr}(B^t(\alpha A_1 + \beta A_2)) \\ &= \operatorname{tr}(\alpha B^t A_1 + \beta B^t A_2) \\ &= \alpha \operatorname{tr}(B^t A_1) + \beta \operatorname{tr}(B^t A_2) \\ &= \alpha \langle A_1, B \rangle + \beta \langle A_2, B \rangle. \end{aligned}$$

③ (cont.)

③ Let  $A = (a_{ij})$ . Then  $A^t = (b_{ij})$  where  $b_{ij} = a_{ji}$ .

And we get  $A^t A = (c_{ij})$  where  $c_{ij} = \sum_{k=1}^n b_{ik} a_{kj}$   
 $= \sum_{k=1}^n a_{ki} a_{kj}$

$$\text{thus } \text{tr}(A^t A) = \sum_{i=1}^n \sum_{k=1}^n a_{ki}^2.$$

As a sum of squares it is certainly non-negative. And it equals zero exactly when each  $a_{ik} = 0$ , i.e. when  $A = 0$ .

It follows from this last computation that

$$\|A\| = \sqrt{\langle A, A \rangle} = \sqrt{\sum_{i,j} a_{ij}^2}$$

To see that  $B = \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$  is an orthonormal basis, we just compute

$$\text{tr} \left( \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}^t \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \right) = 1 = \text{tr} \left( \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right) = \text{tr} \left( \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) \\ = \text{tr} \left( \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right)$$

so all vectors have norm one, and

$$\text{tr} \left( \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}^t \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \right) = 0 = \text{tr} \left( \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}^t \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) = \text{tr} \left( \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) \\ = \text{tr} \left( \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}^t \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) = \text{tr} \left( \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right) \\ = \text{tr} \left( \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix} \right)$$

so the set  $B$  is orthogonal.

④ We begin with the vectors

$$v_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix} \quad v_2 = \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} \quad v_3 = \begin{pmatrix} 1 \\ 1 \\ 2 \\ 4 \end{pmatrix} \quad v_4 = \begin{pmatrix} 1 \\ 2 \\ -4 \\ -3 \end{pmatrix}$$

first we make an orthogonal set

$$w_1 = v_1 = \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}, \quad \langle w_1, w_1 \rangle = 1 + 0 + 1 + 2 = 6$$

$$\|w_1\| = \sqrt{6}$$

$$w_2 = v_2 - \frac{\langle v_2, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1$$

$$= \begin{pmatrix} 1 \\ 1 \\ 1 \\ 1 \end{pmatrix} - \frac{4}{6} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1/3 \\ 1 \\ 1/3 \\ -1/3 \end{pmatrix}, \quad \langle w_2, w_2 \rangle = \frac{1}{9} + 1 + \frac{1}{9} + \frac{1}{9}$$

$$= \frac{12}{9} = \frac{4}{3}$$

$$\|w_2\| = \frac{2}{\sqrt{3}}$$

$$w_3 = v_3 - \frac{\langle v_3, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2 - \frac{\langle v_3, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1$$

$$= \begin{pmatrix} 1 \\ 1 \\ 2 \\ 4 \end{pmatrix} - \frac{2/3}{4/3} \begin{pmatrix} 1/3 \\ 1 \\ 1/3 \\ -1/3 \end{pmatrix} - \frac{11}{6} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 2 \\ 4 \end{pmatrix} - \frac{1}{2} \begin{pmatrix} 1/3 \\ 1 \\ 1/3 \\ -1/3 \end{pmatrix} - \frac{11}{6} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} -1 \\ 1/2 \\ 0 \\ 1/2 \end{pmatrix}, \quad \langle w_3, w_3 \rangle = 1 + \frac{1}{4} + 0 + \frac{1}{4} = \frac{6}{4} = \frac{3}{2}$$

$$\|w_3\| = \sqrt{3/2}$$

$$w_4 = v_4 - \frac{\langle v_4, w_3 \rangle}{\langle w_3, w_3 \rangle} w_3 - \frac{\langle v_4, w_2 \rangle}{\langle w_2, w_2 \rangle} w_2 - \frac{\langle v_4, w_1 \rangle}{\langle w_1, w_1 \rangle} w_1$$

$$= \begin{pmatrix} 1 \\ 2 \\ -4 \\ -3 \end{pmatrix} - \frac{(-3/2)}{3/2} \begin{pmatrix} -1 \\ 1/2 \\ 0 \\ 1/2 \end{pmatrix} - \frac{2}{4/3} \begin{pmatrix} 1/3 \\ 1 \\ 1/3 \\ -1/3 \end{pmatrix} - \frac{(-9)}{6} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix}$$

$$= \begin{pmatrix} 1 \\ 2 \\ -4 \\ -3 \end{pmatrix} + \begin{pmatrix} -1 \\ 1/2 \\ 0 \\ 1/2 \end{pmatrix} - \frac{3}{2} \begin{pmatrix} 1/3 \\ 1 \\ 1/3 \\ -1/3 \end{pmatrix} + \frac{3}{2} \begin{pmatrix} 1 \\ 0 \\ 1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ -3 \\ 1 \end{pmatrix} \quad (\text{oops})$$

④ (cont.)

To get an orthonormal basis, we divide these vectors by their lengths. The only one yet to compute is

$$\langle w_4, w_4 \rangle = 1 + 1 + 9 + 1 = 12, \quad \|w_4\| = \sqrt{12}$$

so our orthonormal basis is

$$u_1 = \begin{pmatrix} 1/\sqrt{6} \\ 0 \\ 1/\sqrt{6} \\ 2/\sqrt{6} \end{pmatrix}, \quad \cancel{u_2 = \begin{pmatrix} 2/\sqrt{6} \\ 1/\sqrt{6} \\ 1/\sqrt{6} \\ 1/\sqrt{6} \end{pmatrix}}, \quad u_2 = \begin{pmatrix} 1/2\sqrt{3} \\ \sqrt{3}/2 \\ 1/2\sqrt{3} \\ -1/2\sqrt{3} \end{pmatrix}$$

$$u_3 = \begin{pmatrix} -\sqrt{2/3} \\ 1/2\sqrt{2/3} \\ 0 \\ 1/2\sqrt{2/3} \end{pmatrix}, \quad u_4 = \begin{pmatrix} 1/\sqrt{12} \\ 1/\sqrt{12} \\ -3/\sqrt{12} \\ 1/\sqrt{12} \end{pmatrix}$$

⑤ To do this problem: One way is to pick any basis  $v_1, \dots, v_n$  of  $\mathbb{R}^n$ , then apply Gram-Schmidt to produce an orthonormal basis of  $\mathbb{R}^n$ . By the theorem from class on Monday, the matrix with these vectors as its columns is orthogonal!

There are lots of possible answers, and they can be checked by computing that  $X^T X = I$ .

for example, a  $4 \times 4$  matrix can be made by the last problem.

Cleaned up  $\rightarrow$   $\begin{pmatrix} 1/\sqrt{6} & 1/\sqrt{12} & -2/\sqrt{6} & 1/\sqrt{12} \\ 0 & 3/\sqrt{12} & 1/\sqrt{6} & 1/\sqrt{12} \\ 1/\sqrt{6} & 1/\sqrt{12} & 0 & -3/\sqrt{12} \\ 1/\sqrt{6} & -1/\sqrt{12} & 1/\sqrt{6} & 1/\sqrt{12} \end{pmatrix}$  is orthogonal.

⑥ (1) Let  $B = \{v_1, \dots, v_n\}$  be a basis of  $V$ .

We apply Gram-Schmidt to produce an orthogonal basis  $\{w_1, \dots, w_n\} = B'$ .

$$w_1 = v_1$$

$$w_2 = v_2 - c_{21}w_1$$

$$w_3 = v_3 - c_{32}w_2 - c_{31}w_1$$

⋮

$$w_n = v_n - c_{nn-1}w_{n-1} - \dots - c_{n1}w_1$$

the  $c_{ij}$ 's are ~~to~~ scalars...

Two ways from here:

□ bring the  $w_i$  terms on the right over to the left! Obtain

$$v_1 = w_1$$

$$v_2 = c_{21}w_1 + w_2$$

$$v_3 = c_{31}w_1 + c_{32}w_2 + w_3$$

⋮

$$v_n = c_{n1}w_1 + c_{n2}w_2 + \dots + w_n$$

The change of basis matrix from  $B'$  to  $B$  is the transpose of this array. Call it  $Q$ . Clearly,  $Q$  is upper triangular.

Now, the change of basis matrix from  $B$  to  $B'$  is  $P = Q^{-1}$ , and the inverse of an upper triangular matrix is upper triangular (can you prove that?) so we're done

⑥ (cont.)

[2] Use the upper equations to substitute into lower equations in the Gram-Schmidt equations to see that for some other scalars  $a_{ij}$

$$W_1 = V_1$$

$$W_2 = a_{21}V_1 + V_2$$

$$W_3 = a_{31}V_1 + a_{32}V_2 + V_3$$

⋮

$$W_n = a_{n1}V_1 + \dots + V_n$$

This exhibits the change of basis matrix from  $B$  to  $B'$  as the transpose  $P$  of this array, which is clearly upper triangular.

(2) First note that in (1) we could have also normalized our vectors  $w_i$  to have an orthonormal basis, and though this changes the actual coefficients it doesn't change the triangularity. So we may assume (1) with  $B'$  an onb.

Let  $A = (v_1 \dots v_n)$  be invertible. Then the columns  $v_1, \dots, v_n$  are a basis. By (1), there is an onb  $w_1, \dots, w_n$  of  $\mathbb{R}^n$  such that the change of basis  $P$  from  $v$ 's to  $w$ 's is upper triangular. Recall,  $v_i = Pw_i$  by the change of basis theorem. Now we have  $A = (v_1 \dots v_n) = (Pw_1 \dots Pw_n) = P(w_1 \dots w_n) = PK$  where  $K = (w_1 \dots w_n)$  has orthonormal columns and is hence orthogonal.